

On Pohlke's type projections in the hyperbolic case

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November 21, 2022

Abstract

Let OP_1, OP_2, OP_3 be three non-parallel segments in a plane. The purpose of this note is to extend the results obtained in [6] and [7] determining the common inscribed ellipse and the common circumscribing hyperbola (with center O) of the three ellipses having as conjugate semi-diameters the pairs (OP_1, OP_2) , (OP_2, OP_3) and (OP_3, OP_1) .

Mathematics Subject Classification: Primary: 51N10, 51N20; Secondary: 51N05.

Keywords: Hyperbolic Pohlke's projection, inscribed ellipse, circumscribing hyperbola.

1 Introduction

Given three non-parallel segments OP_1, OP_2, OP_3 originating at O and lying in a plane ω , we consider the three concentric ellipses $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}$ determined by the pairs of conjugate semi-diameter (OP_1, OP_2) , (OP_2, OP_3) and (OP_3, OP_1) , respectively.

It is a simple consequence of Pohlke's fundamental theorem ([1], [4], [5], [8]) that there is *always* an ellipse with center O , here indicated with \mathcal{E}_P (Pohlke's ellipse), which circumscribes $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}$ and \mathcal{E}_{P_3, P_1} ([2], [3], [6]).¹ It is possible to show (see [7, Thm. 3.8]) that if

$$\overrightarrow{OP_3} = h\overrightarrow{OP_1} + k\overrightarrow{OP_2}, \quad (1.1)$$

then a pair of conjugate semi-diameters of \mathcal{E}_P is given by the vectors

$$\overrightarrow{OV} = \frac{k\overrightarrow{OP_1} - h\overrightarrow{OP_2}}{\sqrt{h^2 + k^2}}, \quad \overrightarrow{OW} = \sqrt{\frac{1 + h^2 + k^2}{h^2 + k^2}} \overrightarrow{OP_3}. \quad (1.2)$$

Again supposing that OP_1, OP_2, OP_3 are non-parallel, if we further assume that

$$(h + k + 1)(h + k - 1)(h - k + 1)(h - k - 1) > 0, \quad (1.3)$$

then there is a second concentric ellipse, other than \mathcal{E}_P , which circumscribes $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}$ and \mathcal{E}_{P_3, P_1} . We call this new ellipse the *secondary Pohlke's ellipse* \mathcal{E}_S . It turns out that \mathcal{E}_S is unique and that (1.3) is also a necessary condition. See [6], [7] and [10].

¹ If OQ_1, OQ_2, OQ_3 are congruent, mutually orthogonal segments and $\Pi : \mathbb{R}^3 \rightarrow \omega$ is a parallel projection such that $\Pi(Q_i) = P_i$ for $i = 1, 2, 3$, then the ellipse \mathcal{E}_P is the contour of $\Pi(S)$, where $S \subset \mathbb{R}^3$ is the sphere with center O containing Q_1, Q_2, Q_3 . The existence and uniqueness of \mathcal{E}_P derive from Pohlke's theorem.

It is worth noting that in both the above cases the circumscribing ellipse (\mathcal{E}_P or \mathcal{E}_S) is obtained as the contour of the parallel projection, into the drawing plane ω , of a suitable sphere with center O . In the present paper we investigated what happens when (1.3) does not hold, i.e., when the secondary Pohlke's ellipse \mathcal{E}_S does not exist. For this purpose we use the parallel projection, on the plane ω , of a suitable hyperboloid. We show that if

$$(h+k+1)(h+k-1)(h-k+1)(h-k-1) < 0, \quad (1.4)$$

and

$$f(h, k) = (h^2 + k^2 - 1)[(h^2 - k^2)^2 - 1] \neq 0, \quad (1.5)$$

then there is a third conic, with center O , tangent to \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} and \mathcal{E}_{P_3, P_1} .

Further, it turns out that this conic is an ellipse, say \mathcal{E}_I , inscribed in \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} , \mathcal{E}_{P_3, P_1} if h, k are such that $f(h, k) < 0$. Conversely, it is a hyperbola, say \mathcal{H}_C , which circumscribes the three ellipses \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} , \mathcal{E}_{P_3, P_1} if $f(h, k) > 0$.² Both \mathcal{E}_I and \mathcal{H}_C , when they exist, are unique and the conditions (1.4), (1.5) are also necessary. But, unlike what happens in the previous two cases (i.e., for the ellipses \mathcal{E}_P and \mathcal{E}_S), now the conics \mathcal{E}_I and \mathcal{H}_C are obtained as the contour of the parallel projection of a suitable one-sheeted hyperboloid centered in O and with axis perpendicular to the plane ω .

1.1 Definitions and Main Results

In the Euclidean space \mathbb{E}^3 we fix a plane ω and a system of coordinates such that

$$\omega \stackrel{\text{def}}{=} \{(x, y, z) \in \mathbb{R}^3 \mid z = 0\}. \quad (1.6)$$

We denote with $O \in \omega$ the origin of coordinates.

Definition 1.1 *Given a plane π and a non-zero vector \mathbf{w} , $\mathbf{w} \nparallel \pi$, we say that P, Q are obliquely symmetrical with respect to π , in the direction of \mathbf{w} , if*

$$PQ \parallel \mathbf{w} \quad \text{and} \quad \frac{P+Q}{2} \in \pi. \quad (1.7)$$

Definition 1.2 *Given a non-zero vector*

$$\mathbf{v} = l\mathbf{i} + m\mathbf{j} + n\mathbf{k} \quad (l, m, n \in \mathbb{R}), \quad (1.8)$$

we denote with $\pi_{\mathbf{v}}$ the plane

$$\pi_{\mathbf{v}} : lx + my - nz = 0. \quad (1.9)$$

When $\mathbf{v} \nparallel \pi_{\mathbf{v}}$ (i.e., if $l^2 + m^2 - n^2 \neq 0$), we say that P, P' are $\pi_{\mathbf{v}}$ -symmetric if P, P' are obliquely symmetrical with respect to the plane $\pi_{\mathbf{v}}$, in the direction of \mathbf{v} .

For $\rho > 0$, we denote with $\mathcal{H} = \mathcal{H}(\rho)$ be the one-sheeted hyperboloid

$$\mathcal{H}(\rho) \stackrel{\text{def}}{=} \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 - z^2 = \rho^2\}. \quad (1.10)$$

Furthermore, given a point $P \in \mathcal{H}$, we indicate with $T_{\mathcal{H}}(P)$ the tangent plane to \mathcal{H} at P . Namely, if $P = P(x_P, y_P, z_P)$, the plane

$$T_{\mathcal{H}}(P) : x_P x + y_P y - z_P z = \rho^2. \quad (1.11)$$

² \mathcal{H}_C circumscribes \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} , \mathcal{E}_{P_3, P_1} in the sense of Def. 2.8 below.

³ With $\frac{P+Q}{2}$ we will indicate the midpoint of the segment PQ .

Definition 1.3 Let \mathbf{v} be a non-zero vector such that $\mathbf{v} \not\parallel \omega$. We denote with

$$\Pi_{\mathbf{v}} : \mathbb{R}^3 \longrightarrow \omega \quad (1.12)$$

the parallel projection onto ω , in the direction of \mathbf{v} . If $\mathbf{v} \not\parallel \omega$ and $\mathbf{v} = l\mathbf{i} + m\mathbf{j} + n\mathbf{k}$, we say that $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ is non-degenerate for \mathcal{H} (or, simply, non-degenerate) if $l^2 + m^2 - n^2 \neq 0$. Similarly, we say that \mathbf{v} gives a non-degenerate projection direction.

Definition 1.4 Let $OP_1, OP_2, OP_3 \subset \omega$ be three segments which are not contained in a line.

A non-degenerate parallel projection $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ is a hyperbolic Pohlke's projection for OP_1, OP_2, OP_3 if there are a hyperboloid $\mathcal{H} = \mathcal{H}(\rho)$, for some $\rho > 0$, and three points $Q_1, Q_2, Q_3 \in \mathcal{H}$ such that

$$\Pi_{\mathbf{v}}(Q_i) = P_i \quad (1 \leq i \leq 3), \quad (1.13)$$

$$OQ_1 \parallel T_{\mathcal{H}}(Q_2), OQ_2 \parallel T_{\mathcal{H}}(Q_3) \text{ and } OQ_3 \parallel T_{\mathcal{H}}(Q'_1), \quad (1.14)$$

where $Q'_1 \in \mathcal{H}$ is $\pi_{\mathbf{v}}$ -symmetric to Q_1 in the sense of Def. 1.2 above.

If the segments OP_1, OP_2, OP_3 are not parallel to each other, we can think (OP_1, OP_2) , (OP_2, OP_3) and (OP_3, OP_1) as pairs of conjugate semi-diameters of three concentric ellipses.

Definition 1.5 Given $OP, OQ \subset \omega$, $OP \not\parallel OQ$, we denote with $\mathcal{E}_{P,Q}$ the ellipse with OP, OQ as conjugate semi-diameters.

Then, considering the ellipses \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} and \mathcal{E}_{P_3, P_1} , we give the following definition:

Definition 1.6 Suppose OP_1, OP_2, OP_3 are non-parallel. A conic \mathcal{C} , with center O , is a hyperbolic Pohlke's conic for OP_1, OP_2, OP_3 if one of the following holds:

- \mathcal{C} is an ellipse inscribed in \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} , \mathcal{E}_{P_3, P_1} .⁴
- \mathcal{C} is a hyperbola which circumscribes \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} , \mathcal{E}_{P_3, P_1} .⁴

Theorem 1.7 Suppose the segments OP_1, OP_2, OP_3 are non-parallel. Then the following three properties are equivalent:

- (1) there is a hyperbolic Pohlke's projection $\Pi_{\mathbf{v}}$ for OP_1, OP_2, OP_3 ;
- (2) there is a hyperbolic Pohlke's conic \mathcal{C} for OP_1, OP_2, OP_3 ;
- (3) $\overrightarrow{OP_3} = h\overrightarrow{OP_1} + k\overrightarrow{OP_2}$ with h, k satisfying the conditions

$$f(h, k) \stackrel{\text{def}}{=} (h^2 + k^2 - 1)[(h^2 - k^2)^2 - 1] \neq 0 \quad (1.15)$$

and

$$g(h, k) \stackrel{\text{def}}{=} (h + k + 1)(h + k - 1)(h - k + 1)(h - k - 1) < 0. \quad (1.16)$$

⁴ In other words, we require that \mathcal{C} be tangent to the three ellipses \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} , \mathcal{E}_{P_3, P_1} and that

- a) $\mathcal{C} \subset \mathbf{int}(\mathcal{E}_{P_1, P_2}) \cap \mathbf{int}(\mathcal{E}_{P_2, P_3}) \cap \mathbf{int}(\mathcal{E}_{P_3, P_1})$, if \mathcal{C} is an ellipse;
- b) $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1} \subset \mathbf{int}(\mathcal{C})$, if \mathcal{C} is a hyperbola.

Here, given a central conic \mathcal{C} (i.e., an ellipse or a hyperbola) in a plane π , we denote with $\mathbf{int}(\mathcal{C})$ (interior of \mathcal{C}) the closure in π of the connected component of $\pi \setminus \mathcal{C}$ containing the center of \mathcal{C} . See Defs. 2.7, 2.8 below.

If the above conditions are true, the conic \mathcal{C} is unique and it turns out that \mathcal{C} is an ellipse if $f(h, k) < 0$, while \mathcal{C} is a hyperbola if $f(h, k) > 0$. The projection $\Pi_{\mathbf{v}}$ is unique up to symmetry with respect to the plane ω .⁵ Besides,

$$\mathcal{C} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}) \quad (1.17)$$

where $\mathcal{H}, \pi_{\mathbf{v}}$ satisfy the conditions of Def. 1.4.

If OP_1, OP_2, OP_3 are not contained in a line but two of them are parallel, in particular if one of them vanishes, we need to introduce degenerate ellipses.⁶

Definition 1.8 If OP, OQ do not both vanish and $OP \parallel OQ$, the degenerate ellipse $\mathcal{E}_{P,Q}$ is the segment MN parallel to OP, OQ such that

$$|MN|^2 = 4(|OP|^2 + |OQ|^2) \quad \text{and} \quad \frac{M+N}{2} = O. \quad (1.18)$$

Given a central conic \mathcal{C} , with center O , we say that \mathcal{C} circumscribes the degenerate ellipse $\mathcal{E}_{P,Q}$ (or that $\mathcal{E}_{P,Q}$ is inscribed in \mathcal{C}) if $M, N \in \mathcal{C}$.⁷

Now we can reformulate Def. 1.6 just saying that:

Definition 1.9 If OP_1, OP_2, OP_3 are not contained in a line but two of them are parallel, a hyperbolic Pohlke's conic for OP_1, OP_2, OP_3 is a hyperbola, with center O , circumscribing the three (eventually degenerate) ellipses $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}$.

Using the Def. 1.9, instead of Def. 1.6, we can state the following:

Theorem 1.10 Suppose OP_1, OP_2, OP_3 are not contained in a line. If two of them are parallel, then there are infinitely many, distinct hyperbolic Pohlke's projections (conics) if these two segments are equal (i.e., congruent), none if they are different.

2 Some basic geometric facts

We shall prove here a number of facts about the one-sheeted hyperboloid $\mathcal{H} = \mathcal{H}(\rho)$ defined in (1.10). We start with some symmetry properties.

Claim 2.1 Let $\pi_{\mathbf{v}}$ be the plane introduced in Def. 1.2 and let us suppose that $l^2 + m^2 - n^2 \neq 0$. Then \mathcal{H} is $\pi_{\mathbf{v}}$ -symmetric (i.e., $P \in \mathcal{H} \Rightarrow P' \in \mathcal{H}$).

Proof. Indeed, let r be any line parallel to \mathbf{v} , that is,

$$r : \begin{cases} x = x_o + lt \\ y = y_o + mt \\ z = z_o + nt \end{cases} \quad (t \in \mathbb{R}), \text{ for a suitable } P(x_o, y_o, z_o). \quad (2.1)$$

⁵ In the sense that, in Def. 1.4, the hyperboloid $\mathcal{H}(\rho)$ is unique and the projection direction (represented by the vector \mathbf{v}) is unique up to orthogonal symmetry (i.e., the usual symmetry) with respect to ω .

⁶ We assume, by convention, that the null segment is parallel to any other segment. Degenerate ellipses were introduced in [1, pp. 372-373]. See also Defs. 3.1, 3.3 of [6].

⁷ Note that $M, N \in \mathcal{C} \Rightarrow \mathcal{E}_{P,Q} \subset \text{int}(\mathcal{C})$ See Def. 2.7 below.

Introducing the expressions (2.1) into the equation of \mathcal{H} , we see that the points of $r \cap \mathcal{H}$ are determined by the real solutions of

$$(l^2 + m^2 - n^2)t^2 + 2(lx_o + my_o - nz_o)t + x_o^2 + y_o^2 - z_o^2 = \rho^2. \quad (2.2)$$

Since $l^2 + m^2 - n^2 \neq 0$, equation (2.2) is of second degree with roots t_1, t_2 such that

$$\frac{t_1 + t_2}{2} = -\frac{lx_o + my_o - nz_o}{l^2 + m^2 - n^2}. \quad (2.3)$$

Now, if $P \in \mathcal{H}$, the solutions of (2.2) are

$$t_1 = 0 \quad \text{and} \quad t_2 = -2 \frac{lx_o + my_o - nz_o}{l^2 + m^2 - n^2}. \quad (2.4)$$

Hence $r \cap \mathcal{H} = \{P(t_1), P(t_2)\}$ with $P(t_1) = P$ and $P(t_2)$ such that

$$\frac{P(t_1) + P(t_2)}{2} = P\left(\frac{t_1 + t_2}{2}\right) \in \pi_{\mathbf{v}}, \quad (2.5)$$

because of (2.1), (2.3). Thus $P(t_2) = P'$. \square

Remark 2.2 *From the proof of Claim 2.1 one can also see that r is tangent to \mathcal{H} at P iff $P \in \mathcal{H} \cap \pi_{\mathbf{v}}$. In fact, if $P \in \mathcal{H}$, we have $t_1 = t_2 \Leftrightarrow lx_o + my_o - nz_o = 0$.*

Definition 2.3 *Let $\mathbf{v} = li + mj + nk$ with $l^2 + m^2 - n^2 \neq 0$. We indicate with $\mathbf{S}_{\mathbf{v}}$ the map associated to the oblique symmetry with respect to $\pi_{\mathbf{v}}$, in the direction of \mathbf{v} . That is the map*

$$P(x, y, z) \xrightarrow{\mathbf{S}_{\mathbf{v}}} P'(x', y', z'), \quad (2.6)$$

given by

$$\mathbf{S}_{\mathbf{v}}(x, y, z) = (x - 2\lambda l, y - 2\lambda m, z - 2\lambda n) \quad \text{with} \quad \lambda = \frac{lx + my - nz}{l^2 + m^2 - n^2}. \quad \square \quad (2.7)$$

Note that, according to Def. 2.3, $\mathbf{S}_{\mathbf{k}}$ represents the orthogonal symmetry (i.e., the usual symmetry) with respect to the plane ω . Besides, we observe that

Remark 2.4 *We can also get Claim 2.1 directly from the oblique symmetry $\mathbf{S}_{\mathbf{v}}$ introduced in Def. 2.3. Indeed, it is easy to see that $\mathbf{S}_{\mathbf{v}}(P) \in \mathcal{H}$ iff $P \in \mathcal{H}$.*

2.1 The intersection of \mathcal{H} with the plane $\pi_{\mathbf{v}}$

If $\pi_{\mathbf{v}}$ is the plane introduced in Def. 1.2, it is clear that $\mathcal{H} \cap \pi_{\mathbf{v}}$ is non-empty, symmetric with respect to O and such that $O \notin \mathcal{H} \cap \pi_{\mathbf{v}}$. Thus $\mathcal{H} \cap \pi_{\mathbf{v}}$ must be a central conic in $\pi_{\mathbf{v}}$ with center O , if it is non-degenerate.⁸ On the other hand, if $\mathcal{H} \cap \pi_{\mathbf{v}}$ is degenerate, then it is a pair of distinct, parallel lines which are symmetric with respect to O . More precisely,

Claim 2.5 *Let $\pi_{\mathbf{v}}$ be the plane introduced in Def. 1.2, then*

⁸ That is, a non-degenerate conic with center, i.e., an ellipse or a hyperbola.

- (1) $\mathcal{H} \cap \pi_{\mathbf{v}}$ is an ellipse $\Leftrightarrow l^2 + m^2 - n^2 < 0$.⁹
(2) $\mathcal{H} \cap \pi_{\mathbf{v}}$ is a pair of distinct, parallel lines $\Leftrightarrow l^2 + m^2 - n^2 = 0$.
(3) $\mathcal{H} \cap \pi_{\mathbf{v}}$ is a hyperbola $\Leftrightarrow l^2 + m^2 - n^2 > 0$.

Proof. \Leftarrow To begin with, let us suppose $n = 0$. Then we have $l^2 + m^2 - n^2 > 0$ and

$$\pi_{\mathbf{v}} : lx + my = 0.$$

From the identity

$$(l^2 + m^2)(x^2 + y^2) \equiv (lx + my)^2 + (mx - ly)^2, \quad (2.8)$$

we deduce that $\mathcal{H} \cap \pi_{\mathbf{v}}$ is given by the points $P(x, y, z) \in \pi_{\mathbf{v}}$ such that

$$\frac{(mx - ly)^2}{l^2 + m^2} - z^2 = \rho^2. \quad (2.9)$$

But (2.9) represents a hyperbola in $\pi_{\mathbf{v}}$, because $h = \frac{mx-ly}{\sqrt{l^2+m^2}}$ and $k = z$ may be considered as coordinates in $\pi_{\mathbf{v}}$. Next, let us suppose $n \neq 0$. In this case the coordinates of the points of $\pi_{\mathbf{v}}$ satisfy the relation

$$z = \frac{lx + my}{n}. \quad (2.10)$$

Hence $\mathcal{H} \cap \pi_{\mathbf{v}}$ is given by the points $P(x, y, z) \in \pi_{\mathbf{v}}$ such that

$$(n^2 - l^2)x^2 + (n^2 - m^2)y^2 - 2lmxy = n^2\rho^2. \quad (2.11)$$

Equation (2.11) (with the condition $z = 0$) defines a conic \mathcal{C} , with center O , in the plane ω . Namely, \mathcal{C} is an ellipse if $l^2 + m^2 - n^2 < 0$, while \mathcal{C} is a hyperbola if $l^2 + m^2 - n^2 > 0$. Noting that $\mathcal{H} \cap \pi_{\mathbf{v}}$ is the image of \mathcal{C} via the affine transformation $\mathbf{T} : \omega \rightarrow \pi_{\mathbf{v}}$,

$$(x, y) \xrightarrow{\mathbf{T}} \left(x, y, \frac{lx + my}{n} \right), \quad (2.12)$$

$\mathcal{H} \cap \pi_{\mathbf{v}}$ is an ellipse or a hyperbola depending on whether the quantity $l^2 + m^2 - n^2$ is < 0 or > 0 , respectively. Finally, let us suppose $n \neq 0$ and $l^2 + m^2 - n^2 = 0$. In this last case (2.11) factorizes as

$$(mx - ly + n\rho)(mx - ly - n\rho) = 0, \quad (2.13)$$

because $n^2 - l^2 = m^2$ and $n^2 - m^2 = l^2$. Thus $\mathcal{H} \cap \pi_{\mathbf{v}}$ is a pair of distinct, parallel lines which are symmetric with respect to O .

\Rightarrow The reverse implication is now an immediate consequence of the fact that by proving \Leftarrow we have exhausted all possible cases for the sign of the quantity $l^2 + m^2 - n^2$. \square

For the sake of brevity, we will later say that:

Definition 2.6 \mathcal{C} is an admissible conic if \mathcal{C} is a central conic centered at O , or a pair of distinct, parallel lines which are symmetric with respect to O .

⁹ We will distinguish between circles and ellipses only when strictly necessary. In this case it is not difficult to show that $\mathcal{H} \cap \pi_{\mathbf{v}}$ is a circle $\Leftrightarrow l = m = 0$.

2.2 The projection of \mathcal{H} into the plane $\pi_{\mathbf{v}}$

We will adopt the following terminology:

Definition 2.7 Let $\mathcal{C} \subset \pi$ be a central conic in a plane π , i.e., an ellipse or a hyperbola.

- (1) We denote with $\mathbf{int}(\mathcal{C})$ (interior of \mathcal{C}) the closure in π of the connected component of $\pi \setminus \mathcal{C}$ containing the center of \mathcal{C} .
- (2) We denote also with $\mathbf{ext}(\mathcal{C})$ (exterior of \mathcal{C}) the closure in π of $\pi \setminus \mathbf{int}(\mathcal{C})$.

Definition 2.8 Given two concentric central conics $\mathcal{C}_1, \mathcal{C}_2 \subset \omega$, we will say that \mathcal{C}_1 is inscribed in \mathcal{C}_2 (or, equivalently, that \mathcal{C}_2 circumscribes \mathcal{C}_1) if \mathcal{C}_1 and \mathcal{C}_2 are tangent and $\mathcal{C}_1 \subset \mathbf{int}(\mathcal{C}_2)$.

Remark 2.9 As it is known, in an appropriate coordinate system (say \mathbf{x}, \mathbf{y}) a central conic \mathcal{C} has the simple equation $\lambda \mathbf{x}^2 + \mu \mathbf{y}^2 = 1$, with $\lambda > 0$ and $\mu \neq 0$. Then, we have

$$\begin{aligned} \mathbf{int}(\mathcal{C}) &= \{P(\mathbf{x}, \mathbf{y}) \in \zeta \mid \lambda \mathbf{x}^2 + \mu \mathbf{y}^2 \leq 1\}, \\ \mathbf{ext}(\mathcal{C}) &= \{P(\mathbf{x}, \mathbf{y}) \in \zeta \mid \lambda \mathbf{x}^2 + \mu \mathbf{y}^2 \geq 1\}. \quad \square \end{aligned}$$

If $\mathbf{v} = l\mathbf{i} + m\mathbf{j} + n\mathbf{k}$ provides a non-degenerate projection direction (Def. 1.3), i.e.,

$$l^2 + m^2 - n^2 \neq 0, \quad (2.14)$$

we may consider the parallel projection $\tilde{\Pi}_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \pi_{\mathbf{v}}$ in the direction of \mathbf{v} ; that is

$$\tilde{\Pi}_{\mathbf{v}}(x, y, z) \stackrel{\text{def}}{=} (x - \lambda l, y - \lambda m, z - \lambda n) \quad \text{with} \quad \lambda = \frac{lx + my - nz}{l^2 + m^2 - n^2}. \quad (2.15)$$

Applying Claim 2.5, we have:

Claim 2.10 Let $\tilde{\Pi}_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \pi_{\mathbf{v}}$ be the projection defined by (2.15), then

- (a) $\tilde{\Pi}_{\mathbf{v}}(\mathcal{H}) = \mathbf{ext}(\mathcal{H} \cap \pi_{\mathbf{v}})$ if $\mathcal{H} \cap \pi_{\mathbf{v}}$ is an ellipse, i.e., if $l^2 + m^2 - n^2 < 0$.
- (b) $\tilde{\Pi}_{\mathbf{v}}(\mathcal{H}) = \mathbf{int}(\mathcal{H} \cap \pi_{\mathbf{v}})$ if $\mathcal{H} \cap \pi_{\mathbf{v}}$ is a hyperbola, i.e., if $l^2 + m^2 - n^2 > 0$.

Proof. Indeed, given $P(x_o, y_o, z_o) \in \pi_{\mathbf{v}}$, we have that

$$P \in \tilde{\Pi}_{\mathbf{v}}(\mathcal{H}) \iff \text{equation (2.2) has a real solution.}$$

Since $lx_o + my_o - nz_o = 0$ in $\pi_{\mathbf{v}}$, from (2.2) we see that:

- (a') $P \in \tilde{\Pi}_{\mathbf{v}}(\mathcal{H}) \iff x_o^2 + y_o^2 - z_o^2 \geq \rho^2$, if $\mathcal{H} \cap \pi_{\mathbf{v}}$ is an ellipse.
- (b') $P \in \tilde{\Pi}_{\mathbf{v}}(\mathcal{H}) \iff x_o^2 + y_o^2 - z_o^2 \leq \rho^2$, if $\mathcal{H} \cap \pi_{\mathbf{v}}$ is a hyperbola.

Supposing for the moment $n \neq 0$ and using (2.10), we see that:

$$(a'') \quad x_o^2 + y_o^2 - z_o^2 \geq \rho^2 \Leftrightarrow (n^2 - l^2)x_o^2 + (n^2 - m^2)y_o^2 - 2mlx_o y_o \geq n^2 \rho^2,$$

$$(b'') \quad x_o^2 + y_o^2 - z_o^2 \leq \rho^2 \Leftrightarrow (n^2 - l^2)x_o^2 + (n^2 - m^2)y_o^2 - 2mlx_o y_o \leq n^2 \rho^2,$$

depending on whether $\mathcal{H} \cap \pi_{\mathbf{v}}$ is an ellipse or a hyperbola, respectively. In other words, given $P(x_o, y_o, z_o) \in \pi_{\mathbf{v}}$, we deduce that:

$$(a''') \quad P \in \tilde{\Pi}_{\mathbf{v}}(\mathcal{H}) \Leftrightarrow (x_o, y_o) \text{ is exterior to the ellipse } \mathcal{E} \subset \omega, \text{ with}$$

$$\mathcal{E}: (n^2 - l^2)x^2 + (n^2 - m^2)y^2 - 2mlxy = n^2 \rho^2,$$

$$(b''') \quad P \in \tilde{\Pi}_{\mathbf{v}}(\mathcal{H}) \Leftrightarrow (x_o, y_o) \text{ is interior to the hyperbola } \mathcal{H} \subset \omega, \text{ with}$$

$$\mathcal{H}: (n^2 - l^2)x^2 + (n^2 - m^2)y^2 - 2mlxy = n^2 \rho^2,$$

depending on whether $\mathcal{H} \cap \pi_{\mathbf{v}}$ is respectively an ellipse or a hyperbola.

To conclude, it is now sufficient to observe that in any case the plane $\pi_{\mathbf{v}}$ is the affine image, via the transformation $T: \omega \rightarrow \pi_{\mathbf{v}}$ in (2.12), of the plane ω and that, by (2.10)–(2.11), the same transformation maps the conic $\mathcal{E} \subset \omega$, or $\mathcal{H} \subset \omega$, onto $\mathcal{H} \cap \pi_{\mathbf{v}}$. Hence we also have:

$$(a''''') \quad (x_o, y_o) \text{ is exterior to the ellipse } \mathcal{E} \Leftrightarrow P \text{ is exterior to the ellipse } \mathcal{H} \cap \pi_{\mathbf{v}},$$

$$(b''''') \quad (x_o, y_o) \text{ is interior to the hyperbola } \mathcal{H} \Leftrightarrow P \text{ is interior to the hyperbola } \mathcal{H} \cap \pi_{\mathbf{v}},$$

depending on whether $\mathcal{H} \cap \pi_{\mathbf{v}}$ is respectively an ellipse or a hyperbola.

Finally, let us suppose $n = 0$. In this case $l^2 + m^2 - n^2 > 0$, thus $\mathcal{H} \cap \pi_{\mathbf{v}}$ is a hyperbola in $\pi_{\mathbf{v}}$. Given $P = P(x_o, y_o, z_o) \in \pi_{\mathbf{v}}$, using the identity (2.8) we can rewrite the condition (b'), that is, $x_o^2 + y_o^2 - z_o^2 \leq \rho^2$, in the form

$$(mx_o - ly_o)^2 - (l^2 + m^2)z_o^2 \leq (l^2 + m^2)\rho^2, \quad (2.16)$$

because $P \in \pi_{\mathbf{v}} \Leftrightarrow lx_o + my_o = 0$. Then, introducing in $\pi_{\mathbf{v}}$ the coordinates $h = \frac{mx_o - ly_o}{\sqrt{l^2 + m^2}}$ and $k = z_o$, we immediately see that condition (2.16) is equivalent to

$$h_o^2 - k_o^2 \leq \rho^2 \quad \text{with} \quad h_o = h(x_o, y_o), \quad k_o = z_o. \quad (2.17)$$

This, in turn, is equivalent to saying that $P \in \pi_{\mathbf{v}}$ is interior to the hyperbola $\mathcal{H} \cap \pi_{\mathbf{v}}$. In fact, with the coordinates (h, k) , the equation of $\mathcal{H} \cap \pi_{\mathbf{v}}$ is exactly $h^2 - k^2 = \rho^2$, as one can see from the first part of the proof of Claim 2.5. \square

2.3 The projection of \mathcal{H} and $\mathcal{H} \cap \pi_{\mathbf{v}}$ into the plane ω

To continue we suppose

$$\mathbf{v} = l\mathbf{i} + m\mathbf{j} + n\mathbf{k} \quad \text{with} \quad n \neq 0. \quad (2.18)$$

We can therefore define the projection $\Pi_{\mathbf{v}}: \mathbb{R}^3 \rightarrow \omega$ in the direction of \mathbf{v} . Namely

$$\Pi_{\mathbf{v}}(x, y, z) \stackrel{\text{def}}{=} \left(x - \frac{l}{n}z, y - \frac{m}{n}z, 0 \right). \quad (2.19)$$

Assuming also $l^2 + m^2 - n^2 \neq 0$ the restriction of $\Pi_{\mathbf{v}}$ to the plane $\pi_{\mathbf{v}}: lx + my - nz = 0$ is an affine transformation from $\pi_{\mathbf{v}}$ to ω . Noting that $\Pi_{\mathbf{v}}(O) = O$, taking into account Def. 1.3 and Claim 2.5, we easily have the following:

Corollary 2.11 *Let $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ be non-degenerate, then*

(1) $\Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}})$ is an ellipse centered at $O \Leftrightarrow l^2 + m^2 - n^2 < 0$.¹⁰

(2) $\Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}})$ is a hyperbola centered at $O \Leftrightarrow l^2 + m^2 - n^2 > 0$.

We can then give the following definition:

Definition 2.12 *Let $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ be non-degenerate. We denote with $\mathcal{C}_{\mathbf{v}}$ the conic*

$$\mathcal{C}_{\mathbf{v}} \stackrel{\text{def}}{=} \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}). \quad (2.20)$$

Let us note that

$$\Pi_{\mathbf{v}} = \Pi_{\mathbf{v}} \circ \tilde{\Pi}_{\mathbf{v}},$$

if \mathbf{v} is non-degenerate. Then, from Claim 2.10, we have:

Corollary 2.13 *Let $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ be non-degenerate. Then*

(1) $\Pi_{\mathbf{v}}(\mathcal{H}) = \mathbf{ext}(\mathcal{C}_{\mathbf{v}})$ if $\mathcal{C}_{\mathbf{v}}$ is an ellipse, i.e., if $l^2 + m^2 - n^2 < 0$.

(2) $\Pi_{\mathbf{v}}(\mathcal{H}) = \mathbf{int}(\mathcal{C}_{\mathbf{v}})$ if $\mathcal{C}_{\mathbf{v}}$ is a hyperbola, i.e., if $l^2 + m^2 - n^2 > 0$.

Remark 2.14 *When $l^2 + m^2 - n^2 = 0$ it is easy to see that*

$$\Pi_{\mathbf{v}}(\mathcal{H}) = \omega \setminus \{(x, y, 0) \mid lx + my = 0, x^2 + y^2 \neq \rho^2\}. \quad (2.21)$$

This follows from (2.2) with $P \in \omega$ and $l^2 + m^2 - n^2 = 0$. Namely, the equation

$$2(lx_o + my_o)t + x_o^2 + y_o^2 = \rho^2. \quad (2.22)$$

Indeed, from (2.22) we can see that $r \cap \mathcal{H} = \emptyset$ iff $lx_o + my_o = 0$ and $x_o^2 + y_o^2 \neq \rho^2$. \square

Remembering that $\mathcal{H} = \mathcal{H}(\rho)$, it is also easy to see that:

Claim 2.15 *Suppose $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ is non-degenerate. If l, m are not both 0, then $\mathcal{C}_{\mathbf{v}} \subset \omega$ is central conic, with center O , and major/transverse axis orthogonal to \mathbf{v} . More precisely,*

1) If $l^2 + m^2 - n^2 < 0$, then $\mathcal{C}_{\mathbf{v}}$ is an ellipse, centered at O , with semi axes a, b such that

$$a = \rho, \quad b^2 = \rho^2 \frac{n^2 - l^2 - m^2}{n^2}.$$

2) If $l^2 + m^2 - n^2 > 0$, then $\mathcal{C}_{\mathbf{v}}$ is a hyperbola with transverse semi-axis a and conjugate semi-axis b such that

$$a = \rho, \quad b^2 = \rho^2 \frac{l^2 + m^2 - n^2}{n^2}.$$

If $l = m = 0$ the conic $\mathcal{C}_{\mathbf{v}} \subset \omega$ is merely the circle with center O and radius ρ .

¹⁰ It follows that $\Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}})$ is a circle $\Leftrightarrow l = m = 0$. See Claim 2.15 and Remark 2.17.

Proof. We may suppose that

$$\mathbf{v} = \lambda \mathbf{j} + n \mathbf{k} \quad \text{with} \quad \lambda^2 - n^2 \neq 0, \quad (2.23)$$

since the general case follows by rotating \mathbf{v} , given by (2.23), around the z -axis.

Then, from (2.11) with $l = 0$ and $m = \lambda$, the intersection $\mathcal{H} \cap \pi_{\mathbf{v}}$ is given by the points $P = (x, y, z) \in \pi_{\mathbf{v}}$ such that

$$n^2 x^2 + (n^2 - \lambda^2) y^2 = n^2 \rho^2. \quad (2.24)$$

By (2.23) we have $\pi_{\mathbf{v}} : \lambda y - nz = 0$. This means that $P(x, y, z) \in \mathcal{H} \cap \pi_{\mathbf{v}}$ if and only if

$$x^2 + \left(\frac{n^2 - \lambda^2}{n^2} \right) y^2 = \rho^2, \quad z = \frac{\lambda}{n} y. \quad (2.25)$$

With \mathbf{v} as in (2.23) and $P(x, y, z)$ such that $z = \frac{\lambda}{n} y$, from (2.19) we find

$$\Pi_{\mathbf{v}}(x, y, z) = \left(x, \frac{n^2 - \lambda^2}{n^2} y, 0 \right) \stackrel{\text{def}}{=} (\bar{x}, \bar{y}, \bar{z}). \quad (2.26)$$

Hence the coordinates $(\bar{x}, \bar{y}, \bar{z})$ of the points of $\mathcal{C}_{\mathbf{v}} \subset \omega$ satisfy

$$\bar{x}^2 + \left(\frac{n^2}{n^2 - \lambda^2} \right) \bar{y}^2 = \rho^2, \quad \bar{z} = 0. \quad (2.27)$$

For $\lambda \neq 0$, we deduce that

- If $\lambda^2 - n^2 < 0$, then $\mathcal{C}_{\mathbf{v}}$ is an ellipse with major semi-axis $a = \rho$ and minor semi-axis b such that $b^2 = \rho^2 \frac{n^2 - \lambda^2}{n^2}$. The major semi-axis, being along the x -axis, is orthogonal to the direction of projection, i.e., \mathbf{v} given by (2.23).
- If $\lambda^2 - n^2 > 0$, then $\mathcal{C}_{\mathbf{v}}$ is a hyperbola with transverse semi-axis $a = \rho$ and conjugate semi-axis b such that $b^2 = \rho^2 \frac{\lambda^2 - n^2}{n^2}$. The transverse semi-axis, being along the x -axis, is orthogonal to the direction of projection given by (2.23).

Finally, when $\lambda = 0$, the conclusion (which formally follows from (2.27) with $\lambda = 0$) is immediate because $\pi_{\mathbf{v}} = \pi_{\mathbf{k}} = \omega$. \square

Remark 2.16 From (2.25)–(2.26) it also follows that if

$$\mathbf{v} = \lambda \mathbf{j} + n \mathbf{k} \quad \text{with} \quad \lambda^2 - n^2 = 0, \quad (2.28)$$

then the points $(\bar{x}, \bar{y}, 0)$ of $\Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}})$ satisfy $\bar{x}^2 = \rho^2$, $\bar{y} = 0$. Hence $\Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}})$ reduces to the pair $(\pm \rho, 0, 0)$. For general $\mathbf{v} = l \mathbf{i} + m \mathbf{j} + n \mathbf{k}$, such that $l^2 + m^2 - n^2 = 0$, we find

$$\Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}) = \pm \left(\frac{m \rho}{\sqrt{l^2 + m^2}}, \frac{-l \rho}{\sqrt{l^2 + m^2}}, 0 \right). \quad \square \quad (2.29)$$

Remark 2.17 From Claim 2.15 we can see that given a central conic $\mathcal{C} \subset \omega$, with center O , there are a unique $\rho > 0$ and, up to symmetry with respect to ω , a unique projection direction (represented by the vector \mathbf{v}) such that

$$\mathcal{C} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}) \stackrel{\text{def}}{=} \mathcal{C}_{\mathbf{v}}.$$

Indeed, ρ must be equal to the major/transverse semi-axis of \mathcal{C} (or the radius, if \mathcal{C} is a circle). As for the direction projection, we have:

- If \mathcal{C} is a circle, then the projection direction is given by the vector $\mathbf{v} = \mathbf{k}$.
- If \mathcal{C} is an ellipse with semi-axes OV, OW such that $|OV| < |OW|$ and $\overrightarrow{OV} = p\mathbf{i} + q\mathbf{j}$, then $\rho = |OW|$ and the projection direction is given by the vectors

$$\mathbf{v} = \delta p\mathbf{i} + \delta q\mathbf{j} \pm \mathbf{k} \quad \text{with} \quad \delta = \sqrt{\frac{\rho^2 - p^2 - q^2}{\rho^2(p^2 + q^2)}}. \quad (2.30)$$

- If \mathcal{C} is a hyperbola with conjugate and transverse semi-axes OV, OW respectively and if $\overrightarrow{OV} = p\mathbf{i} + q\mathbf{j}$, then $\rho = |OW|$ and the projection direction is given by the vectors

$$\mathbf{v} = \delta p\mathbf{i} + \delta q\mathbf{j} \pm \mathbf{k} \quad \text{with} \quad \delta = \sqrt{\frac{\rho^2 + p^2 + q^2}{\rho^2(p^2 + q^2)}}. \quad \square \quad (2.31)$$

In addition, it is immediate that:

Claim 2.18 *In all three cases of Rem. 2.17 the vector \mathbf{v} is non-degenerate.*¹¹

Moreover, recalling the Defs. 1.2, 1.3 and 2.6, we have:

Claim 2.19 *Let $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ be non-degenerate. Then*

- 1) *If $\mathcal{C} \subset \Pi_{\mathbf{v}}(\mathcal{H})$ is an admissible conic tangent to $\mathcal{C}_{\mathbf{v}}$, then there are $\pi_{\mathbf{v}}$ -symmetric planes π, π' through the origin O such that $\pi, \pi' \nparallel \mathbf{v}$ and*

$$\mathcal{C} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi) = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi'). \quad (2.32)$$

- 2) *If in 1) we also assume that \mathcal{C} is an ellipse or a hyperbola with conjugate semi-diameters (OP_1, OP_2) , then there are $Q_1, Q'_1, Q_2, Q'_2 \in \mathcal{H}$ such that $\Pi_{\mathbf{v}}^{-1}(P_1) \cap \mathcal{H} = \{Q_1, Q'_1\}$, $\Pi_{\mathbf{v}}^{-1}(P_2) \cap \mathcal{H} = \{Q_2, Q'_2\}$ and $(OQ_1, OQ_2), (OQ'_1, OQ'_2)$ are conjugate semi-diameters of the conics $\mathcal{H} \cap \pi$ and $\mathcal{H} \cap \pi'$, respectively.*

- 3) *Conversely, if π is a plane through the origin O such that $\pi \nparallel \mathbf{v}$ and $\mathcal{H} \cap \pi_{\mathbf{v}} \cap \pi \neq \emptyset$, then $\mathcal{C} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi)$ is an admissible conic, tangent to $\mathcal{C}_{\mathbf{v}}$.*

Proof. 1) Let \mathcal{C} be tangent to $\mathcal{C}_{\mathbf{v}}$ at X_1 and let

$$t \text{ be the common tangent of } \mathcal{C} \text{ and } \mathcal{C}_{\mathbf{v}} \text{ at } X_1. \quad (2.33)$$

Besides, let $X_2 \in \mathcal{C}$ such that $OX_1 \nparallel OX_2$. Since we assume $\mathcal{C} \subset \Pi_{\mathbf{v}}(\mathcal{H})$, we clearly have

$$X_1, X_2 \in \Pi_{\mathbf{v}}(\mathcal{H}). \quad (2.34)$$

¹¹ This is obvious in view of Cor. 2.11 and Rem. 2.16. But, setting $\mathbf{v} = l\mathbf{i} + m\mathbf{j} + n\mathbf{k}$, in the three cases of Rem. 2.17 it is also easy to see that:

$$l^2 + m^2 - n^2 = \begin{cases} -1 & \text{if } \mathcal{C} \text{ is a circle} \\ -\frac{p^2+q^2}{\rho^2} & \text{if } \mathcal{C} \text{ is an ellipse} \\ \frac{p^2+q^2}{\rho^2} & \text{if } \mathcal{C} \text{ is a hyperbola} \end{cases}$$

Thus there are $Y_1 \in \mathcal{H} \cap \pi_{\mathbf{v}}$ and $Y_2 \in \mathcal{H}$ such that

$$\Pi_{\mathbf{v}}(Y_1) = X_1, \quad \Pi_{\mathbf{v}}(Y_2) = X_2 \quad \text{and} \quad OY_1 \not\parallel OY_2. \quad (2.35)$$

To proceed, let π be the plane through the points O, Y_1, Y_2 . It is clear that $\pi \not\parallel \mathbf{v}$, otherwise we would have $OX_1 = \Pi_{\mathbf{v}}(OY_1) \parallel \Pi_{\mathbf{v}}(OY_2) = OX_2$. Hence the restriction

$$\Pi_{\mathbf{v}} \Big|_{\pi} : \pi \longrightarrow \omega \quad \text{defines an affine transformation.} \quad (2.36)$$

By Claim 2.5 (with π instead of $\pi_{\mathbf{v}}$)

$$\mathcal{H} \cap \pi \quad (2.37)$$

is an *admissible* conic. Then, by (2.36),

$$\mathcal{Q} \stackrel{\text{def}}{=} \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi)$$

is also an *admissible* conic and by (2.33) and Cor. 2.13,

$$X_1 \in \mathcal{Q} \quad \text{and} \quad \mathcal{Q} \subset \Pi_{\mathbf{v}}(\mathcal{H}) \quad \implies \quad \mathcal{Q} \text{ has tangent } t \text{ at } X_1.$$

This means that \mathcal{Q} has in common with \mathcal{C} the point X_1 , the tangent t at X_1 and a second point X_2 such that $OX_1 \not\parallel OX_2$. Since \mathcal{C} and \mathcal{Q} are both symmetric with respect to the origin O , it follows that $\mathcal{C} = \mathcal{Q} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi)$.¹³ Furthermore, taking into account that \mathcal{H} is $\pi_{\mathbf{v}}$ -symmetric, if the plane π' is $\pi_{\mathbf{v}}$ -symmetric to π we also find

$$\Pi_{\mathbf{v}}(\mathcal{H} \cap \pi') = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi) = \mathcal{C}. \quad (2.38)$$

Finally, we note that $\pi \not\parallel \mathbf{v} \implies \pi' \not\parallel \mathbf{v}$, because $\pi' \parallel \mathbf{v} \implies \pi' = \pi$, hence $\pi \parallel \mathbf{v}$ (but we can also observe that (2.38) $\implies \pi' \not\parallel \mathbf{v}$).

2) Having already observed that $\pi, \pi' \not\parallel \mathbf{v}$, the thesis follows from (2.38) and from the fact that the restrictions

$$\Pi_{\mathbf{v}} \Big|_{\pi} : \pi \longrightarrow \omega \quad \text{and} \quad \Pi_{\mathbf{v}} \Big|_{\pi'} : \pi' \longrightarrow \omega \quad \text{are affine transformations.} \quad (2.39)$$

More precisely, by (2.38) and (2.39), we can certainly say that there are $Q_1, Q_2 \in \mathcal{H} \cap \pi$ and $Q'_1, Q'_2 \in \mathcal{H} \cap \pi'$ such that

$$\Pi_{\mathbf{v}}(Q_1) = \Pi_{\mathbf{v}}(Q'_1) = P_1, \quad \Pi_{\mathbf{v}}(Q_2) = \Pi_{\mathbf{v}}(Q'_2) = P_2.$$

Thus the pairs (OQ_1, OQ_2) and (OQ'_1, OQ'_2) are conjugate semi-diameters of the conics $\mathcal{H} \cap \pi$ and $\mathcal{H} \cap \pi'$, respectively. On the other hand, it is easy to show that

$$\Pi_{\mathbf{v}}^{-1}(P_i) \cap \mathcal{H} = \{Q_i, Q'_i\} \quad \text{for } i = 1, 2.$$

¹² Note that Y_1 is unique. In fact, assuming $X_1 \in \mathcal{C}$, the line through X_1 and parallel to \mathbf{v} is tangent to \mathcal{H} at a point of $\mathcal{H} \cap \pi_{\mathbf{v}}$. Y_2 is unique up to $\pi_{\mathbf{v}}$ -symmetry, because $\Pi_{\mathbf{v}}^{-1}(X_2) \cap \mathcal{H} = \{Y_2, Y'_2\}$ with Y_2, Y'_2 $\pi_{\mathbf{v}}$ -symmetric; furthermore, $Y_2 = Y'_2 \iff X_2 \in \mathcal{C}$. See Claim 2.1 and Rem. 2.2 above. Finally, being $\Pi_{\mathbf{v}}$ an affine transformation, it follows that $OX_1 \not\parallel OX_2 \implies OY_1 \not\parallel OY_2$.

¹³ The equation of a conic $\mathcal{Q} \subset \{z = 0\}$ that is symmetrical with respect to O , but which does not pass through O , can be expressed in the form $\alpha x^2 + \beta y^2 + \gamma xy = 1$. The coefficients α, β, γ are uniquely determined if (for instance) we know two points $P_1, P_2 \in \mathcal{Q}$ and the tangent t at one of them, provided $OP_1 \not\parallel OP_2$ and $O \notin t$ (if $O \in t$ then \mathcal{Q} does not exist). If $P_1 P_2 \parallel t$ or $P_1 P'_2 \parallel t$ (with P'_2 symmetric to P_2 with respect to O), the conic is degenerate. Namely, in this case $\mathcal{Q} = t \cup t'$, with t' the symmetric of t with respect to O .

Indeed, if $Q_i \neq Q'_i$ there is nothing to prove, because $\Pi_{\mathbf{v}}^{-1}(P_i) \cap \mathcal{H}$ contains at most two elements. Conversely, if $Q_i = Q'_i = Q$, then we have $Q \in \pi_{\mathbf{v}}$ because

$$Q \in \pi \cap \pi' \text{ and } Q \notin \pi_{\mathbf{v}} \implies Q \neq Q' \text{ and then } \mathbf{v} \parallel QQ' \parallel \pi, \quad (2.40)$$

which is a contradiction. But if $Q \in \pi_{\mathbf{v}}$, the set $\Pi_{\mathbf{v}}^{-1}(P_i) \cap \mathcal{H}$ consists of only one element since the line $\Pi_{\mathbf{v}}^{-1}(P_i)$ is then tangent to \mathcal{H} at Q . See Rem. 2.2.

3) Conversely, let π be a plane through the origin O such that $\pi \not\parallel \mathbf{v}$. By Claim 2.5, $\mathcal{H} \cap \pi$ is an admissible conic in π and since we suppose $\pi \not\parallel \mathbf{v}$, it is clear that (2.36) holds.

Thus $\mathcal{C} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi)$ is an admissible conic in ω . Moreover, $\mathcal{C} \cap \mathcal{C}_{\mathbf{v}} \neq \emptyset$ because we assume $\mathcal{H} \cap \pi_{\mathbf{v}} \cap \pi \neq \emptyset$. Taking into account that $\mathcal{C} \subset \Pi_{\mathbf{v}}(\mathcal{H})$, from Cor. 2.13 we then deduce that \mathcal{C} and $\mathcal{C}_{\mathbf{v}}$ are tangent at any point of $\Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}} \cap \pi)$. \square

Remark 2.20 *The condition $\mathcal{H} \cap \pi_{\mathbf{v}} \cap \pi \neq \emptyset$, which appears in 3) of Claim 2.19, is certainly true if at least one of the conics $\mathcal{H} \cap \pi_{\mathbf{v}}$ and $\mathcal{H} \cap \pi$ is an ellipse. For instance, let $\mathcal{E} = \mathcal{H} \cap \pi_{\mathbf{v}}$ be an ellipse. Then*

$$\mathcal{H} \cap \pi_{\mathbf{v}} \cap \pi = \mathcal{E} \cap (\pi_{\mathbf{v}} \cap \pi) \neq \emptyset, \quad (2.41)$$

because \mathcal{E} is an ellipse in $\pi_{\mathbf{v}}$ centered at O and $\pi_{\mathbf{v}} \cap \pi$ contains a line through O in $\pi_{\mathbf{v}}$.

2.4 The case of degenerate ellipses

In Claim 2.19 we have assumed that $\mathcal{C} \subset \Pi_{\mathbf{v}}(\mathcal{H})$ is an admissible conic, tangent to $\mathcal{C}_{\mathbf{v}}$. But in view of the proof of Thm. 1.10 we need also to consider what happen if \mathcal{C} is a degenerate ellipse (in the sense of Def. 1.8) inscribed in $\mathcal{C}_{\mathbf{v}}$, when $\mathcal{C}_{\mathbf{v}}$ is a hyperbola.

Claim 2.21 *Let $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ be non-degenerate and let $\ell \subset \omega$ be a line through the origin O such that $\ell \cap \mathcal{C}_{\mathbf{v}} \neq \emptyset$. Let ζ be the plane through ℓ and parallel to \mathbf{v} . Then $\mathcal{H} \cap \zeta$ is an ellipse (hyperbola) iff $\mathcal{C}_{\mathbf{v}}$ is a hyperbola (ellipse).*

Proof. As in the proof of Claim 2.15 it is enough to prove the result for

$$\mathbf{v} = \lambda \mathbf{j} + n \mathbf{k} \quad \text{with} \quad \lambda^2 - n^2 \neq 0. \quad (2.42)$$

Therefore, taking into account formula (2.27), $\mathcal{C}_{\mathbf{v}} \subset \omega$ has equation

$$x^2 + \left(\frac{n^2}{n^2 - \lambda^2} \right) y^2 = \rho^2 \quad \text{with} \quad \rho > 0. \quad (2.43)$$

Now, by hypothesis, there exists a point $L = L(x_L, y_L, 0) \in \ell \cap \mathcal{C}_{\mathbf{v}}$. By (2.43) the coordinates of L must then satisfy the relation

$$n^2(x_L^2 + y_L^2) - \lambda^2 x_L^2 = (n^2 - \lambda^2)\rho^2. \quad (2.44)$$

On the other hand, ζ is the plane through OL and parallel to \mathbf{v} . Thus ζ has equation

$$\zeta : (ny_L)x - (nx_L)y + (\lambda x_L)z = 0. \quad (2.45)$$

Noting (2.44), by Claim 2.5, we deduce that:

- $\mathcal{H} \cap \zeta$ is an ellipse $\Leftrightarrow n^2 - \lambda^2 < 0 \Leftrightarrow \mathcal{C}_{\mathbf{v}}$ is a hyperbola;
- $\mathcal{H} \cap \zeta$ is a hyperbola $\Leftrightarrow n^2 - \lambda^2 > 0 \Leftrightarrow \mathcal{C}_{\mathbf{v}}$ is an ellipse. □

Claim 2.22 Given $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$, let ζ be a plane through O and parallel to \mathbf{v} . Let $\mathcal{E} \subset \zeta$ be an ellipse with center O and let $\Pi_{\mathbf{v}}(\mathcal{E}) = MN$, for suitable $M, N \in \omega \cap \zeta$.

1) Let (OQ_1, OQ_2) be a pair of conjugate semi-diameters for \mathcal{E} . If $P_1 = \Pi_{\mathbf{v}}(Q_1)$ and $P_2 = \Pi_{\mathbf{v}}(Q_2)$, then we have

$$|MN|^2 = 4(|OP_1|^2 + |OP_2|^2). \quad (2.46)$$

2) If $P_1, P_2 \in \omega \cap \zeta$ satisfy (2.46), then there are $Q_1, \widehat{Q}_1, Q_2, \widehat{Q}_2 \in \mathcal{E}$ such that $\Pi_{\mathbf{v}}^{-1}(P_1) \cap \mathcal{E} = \{Q_1, \widehat{Q}_1\}$, $\Pi_{\mathbf{v}}^{-1}(P_2) \cap \mathcal{E} = \{Q_2, \widehat{Q}_2\}$ and $(OQ_1, OQ_2), (O\widehat{Q}_1, O\widehat{Q}_2)$ are distinct pairs of conjugate semi-diameters for \mathcal{E} .

Proof. 1) To begin with, we introduce orthogonal coordinates h, k in the plane ζ such that $O = (0, 0)$ and

$$\mathcal{E} : \frac{h^2}{a^2} + \frac{k^2}{b^2} = 1 \quad \text{with } a, b > 0. \quad (2.47)$$

In this situation it is well known that OQ_1, OQ_2 are conjugate semi-diameters for \mathcal{E} if and only if there is $\theta \in [0, 2\pi)$ such that

$$Q_1 = (a \cos \theta, b \sin \theta) \quad \text{and} \quad Q_2 = \pm (a \sin \theta, -b \cos \theta).^{14} \quad (2.48)$$

Moreover, since $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ is linear, given a unit vector \mathbf{u} such that $\mathbf{u} \parallel \omega \cap \zeta$, there are $\alpha, \beta \in \mathbb{R}$ (not both zero) such that

$$\overrightarrow{OP_1} = (a\alpha \cos \theta + b\beta \sin \theta) \mathbf{u} \quad \text{and} \quad \overrightarrow{OP_2} = \pm (a\alpha \sin \theta - b\beta \cos \theta) \mathbf{u}, \quad (2.49)$$

for all $\theta \in [0, 2\pi)$. From (2.49) we immediately have

$$|OP_1|^2 + |OP_2|^2 = (a\alpha)^2 + (b\beta)^2 \quad \text{for all } \theta \in [0, 2\pi) \quad (2.50)$$

and, in particular,

$$|OM|^2 = |ON|^2 = (a\alpha)^2 + (b\beta)^2, \quad (2.51)$$

because $\Pi(Q_1) = M$ or N when $\Pi(Q_2) = O$, that is, when OQ_2 is parallel to the projection direction \mathbf{v} . Hence, from (2.51) we deduce that $|MN|^2 = 4(a\alpha)^2 + 4(b\beta)^2$, because $O = \frac{M+N}{2}$.

2) Conversely, let $P_1, P_2 \in \omega \cap \zeta$ such that the relation (2.46) is true. Before proceeding, let's remember that the ellipse \mathcal{E} has oblique symmetry, in the direction of \mathbf{v} , with respect to the line, say $l_{\mathbf{v}}$, through O and parallel to the direction conjugate to that of \mathbf{v} . Thus, if

$$\Pi_{\mathbf{v}}^{-1}(P_1) \cap \mathcal{E} = \{R_1, \widehat{R}_1\} \quad \text{and} \quad \Pi_{\mathbf{v}}^{-1}(P_2) \cap \mathcal{E} = \{R_2, \widehat{R}_2\},$$

it is clear that the points R_1 and R_2 are obliquely symmetrical (in the direction of \mathbf{v} and with respect to $l_{\mathbf{v}}$) to \widehat{R}_1 and \widehat{R}_2 , respectively. In addition, we know that $R_1 = \widehat{R}_1 \Leftrightarrow R_1 \in l_{\mathbf{v}} \Leftrightarrow P_1 = M$ or N (i.e., $P_2 = O$, by (2.46)) and, similarly, for the couple R_2, \widehat{R}_2 .

¹⁴ See [9], p. 39.

Now, starting for instance from R_1 , we certainly have

$$R_1 = (a \cos \theta_1, b \sin \theta_1) \quad \text{for a suitable } \theta_1 \in [0, 2\pi). \quad (2.52)$$

By (2.46) and taking into account (2.49) and (2.50), one of the following must hold:

$$P_2 = \Pi_{\mathbf{v}}(a \sin \theta_1, -b \cos \theta_1) \quad \text{or} \quad P_2 = \Pi_{\mathbf{v}}(-a \sin \theta_1, b \cos \theta_1), \quad (2.53)$$

because in $\omega \cap \zeta$ there are only two points at a distance of $\frac{1}{2}\sqrt{|MN|^2 - 4|OP_1|^2}$ from O . Assuming, for example, that the second of (2.53) holds, we define

$$Q_1 = R_1 = (a \cos \theta_1, b \sin \theta_1) \quad \text{and} \quad Q_2 = (-a \sin \theta_1, b \cos \theta_1).^{15} \quad (2.54)$$

Then, by the condition (2.48) above, (OQ_1, OQ_2) is a pair of conjugate semi-diameters such that $\Pi_{\mathbf{v}}(Q_1) = P_1$ and $\Pi_{\mathbf{v}}(Q_2) = P_2$. Finally, denoting with \widehat{Q}_1 and \widehat{Q}_2 the symmetric to Q_1 and Q_2 respectively, we can easily see that

$$(O\widehat{Q}_1, O\widehat{Q}_2) \quad (2.55)$$

gives a pair of conjugate semi-diameters such that $(O\widehat{Q}_1, O\widehat{Q}_2) \neq (OQ_1, OQ_2)$. Indeed, let us suppose, for instance, that $\widehat{Q}_1 = Q_1$. Then, as we observed above, $P_1 = M$ or N and $P_2 = O$. But, in turn, the condition $P_2 = O$ implies $\widehat{Q}_2 \neq Q_2$. \square

To conclude, we assume that $OP_1, OP_2 \subset \omega$ do not both vanish and that $OP_1 \parallel OP_2$. Then we consider the degenerate ellipse $\mathcal{E}_{P_1, P_2} = MN$, according to Def. 1.8. Applying Claims 2.21 and 2.22, we deduce the following:

Claim 2.23 *Let $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ be non-degenerate and such that $\mathcal{C}_{\mathbf{v}}$ is a hyperbola. Besides, let $\mathcal{E}_{P_1, P_2} = MN$ be a degenerate ellipse inscribed in $\mathcal{C}_{\mathbf{v}}$ and let ζ be the plane through MN and parallel to the projection direction given by \mathbf{v} .*

Then $\mathcal{H} \cap \zeta$ is an ellipse, with center O , such that $\Pi_{\mathbf{v}}(\mathcal{H} \cap \zeta) = \mathcal{E}_{P_1, P_2}$. Furthermore, there are $Q_1, Q'_1, Q_2, Q'_2 \in \mathcal{H} \cap \zeta$ such that $\Pi_{\mathbf{v}}^{-1}(P_1) \cap \mathcal{H} = \{Q_1, Q'_1\}$, $\Pi_{\mathbf{v}}^{-1}(P_2) \cap \mathcal{H} = \{Q_2, Q'_2\}$ and (OQ_1, OQ_2) , (OQ'_1, OQ'_2) are distinct pairs of conjugate semi-diameters of $\mathcal{H} \cap \zeta$.

Proof. Since MN is a segment through the origin O and $M, N \in \mathcal{C}_{\mathbf{v}}$, by Claim 2.21 we know that $\mathcal{E} = \mathcal{H} \cap \zeta$ is an ellipse, with center O . Then we can easily see that

$$\Pi_{\mathbf{v}}(\mathcal{E}) = \mathcal{E}_{P_1, P_2}. \quad (2.56)$$

Indeed, assuming $\mathcal{E}_{P_1, P_2} = MN$ inscribed in the hyperbola $\mathcal{C}_{\mathbf{v}}$, we have: $\mathcal{E}_{P_1, P_2} \subset \Pi_{\mathbf{v}}(\mathcal{E})$, because $\mathcal{E}_{P_1, P_2} \subset \mathbf{int}(\mathcal{C}_{\mathbf{v}})$, and also $\mathcal{E}_{P_1, P_2} \supset \Pi_{\mathbf{v}}(\mathcal{E})$ because $M, N \in \mathcal{C}_{\mathbf{v}}$. To proceed, we recall that $\mathcal{E}_{P_1, P_2} = MN$ implies

$$|MN|^2 = 4(|OP_1|^2 + |OP_2|^2). \quad (2.57)$$

Moreover, we note that

$$\Pi_{\mathbf{v}}^{-1}(P_i) \cap \mathcal{H} = \Pi_{\mathbf{v}}^{-1}(P_i) \cap \mathcal{E} \quad \text{for } i = 1, 2$$

and that \mathcal{E} has oblique symmetry, in the direction of \mathbf{v} , with respect to the line $l_{\mathbf{v}} = \zeta \cap \pi_{\mathbf{v}}$.¹⁶ We can therefore apply part 2) of Claim 2.22 with $\mathcal{E} = \mathcal{H} \cap \zeta$ and $l_{\mathbf{v}} = \zeta \cap \pi_{\mathbf{v}}$ and this immediately gives the thesis. \square

¹⁵ Clearly, we have $Q_2 = R_2$ or \widehat{R}_2 .

¹⁶ It turns out that $l_{\mathbf{v}} = \zeta \cap \pi_{\mathbf{v}}$ is the line, through O , parallel to the direction conjugate to that of \mathbf{v} .

2.5 Some properties of the tangent planes of \mathcal{H}

Definition 2.24 Given $P \in \mathcal{H}$, we denote with $T_{\mathcal{H}}(P)$ the tangent plane to \mathcal{H} at P .

If $P \in \mathcal{H}$, $P = P(x_P, y_P, z_P)$, we recall that

$$T_{\mathcal{H}}(P) : x_P x + y_P y - z_P z = \rho^2. \quad (2.58)$$

Claim 2.25 If $P, Q \in \mathcal{H}$ and O is the origin of coordinates, then

$$OP \parallel T_{\mathcal{H}}(Q) \Leftrightarrow OQ \parallel T_{\mathcal{H}}(P). \quad (2.59)$$

Proof. Indeed, given $P = P(x_P, y_P, z_P) \in \mathcal{H}$ and $Q = Q(x_Q, y_Q, z_Q)$, we have that

$$OQ \parallel T_{\mathcal{H}}(P) \Leftrightarrow x_P x_Q + y_P y_Q - z_P z_Q = 0. \quad (2.60)$$

But the last condition of (2.60) is symmetric with respect to P and Q if $P, Q \in \mathcal{H}$. \square

Taking into account the oblique symmetry of \mathcal{H} with respect to the plane $\pi_{\mathbf{v}}$ (Def. 1.2), applying Claim 2.25 we easily get the following:

Corollary 2.26 If $P, Q \in \mathcal{H}$ and P', Q' are $\pi_{\mathbf{v}}$ -symmetric to P, Q respectively, then

$$OP \parallel T_{\mathcal{H}}(Q) \Leftrightarrow OP' \parallel T_{\mathcal{H}}(Q') \quad (2.61)$$

and

$$OP \parallel T_{\mathcal{H}}(Q') \Leftrightarrow OQ \parallel T_{\mathcal{H}}(P'). \quad (2.62)$$

Proof. Recalling Def. 2.3 and Rem. 2.4, we easily have

$$S_{\mathbf{v}}(T_{\mathcal{H}}(Q)) = T_{\mathcal{H}}(Q'), \quad (2.63)$$

where $S_{\mathbf{v}}$ is the oblique symmetry with respect to the plane $\pi_{\mathbf{v}}$, in the direction of \mathbf{v} . This immediately gives (2.61). Then (2.62) follows from (2.61) and Claim 2.25. \square

Definition 2.27 Assuming $OP \nparallel OQ$, we denote with $\langle O, P, Q \rangle$ the plane through the origin O and the points P, Q . With $\mathcal{C}(P, Q)$ we indicate the admissible conic

$$\mathcal{C}(P, Q) \stackrel{\text{def}}{=} \mathcal{H} \cap \langle O, P, Q \rangle. \quad (2.64)$$

Moreover, given $R \in \mathcal{C}(P, Q)$, we will denote with $T_{\mathcal{C}(P, Q)}(R) \subset \langle O, P, Q \rangle$ the tangent line to $\mathcal{C}(P, Q)$ passing through the point R .

Remark 2.28 By (2.58) and (2.60), if $P \in \mathcal{H}$ then $OP \nparallel T_{\mathcal{H}}(P)$. More generally,

$$P, Q \in \mathcal{H} \text{ and } OQ \parallel T_{\mathcal{H}}(P) \Rightarrow OP \nparallel OQ, \quad (2.65)$$

because $OP \parallel OQ \Rightarrow OP \parallel T_{\mathcal{H}}(P)$. Further, if $OP \nparallel OQ$ and $R \in \mathcal{H}$ then

$$T_{\mathcal{H}}(R) \cap \langle O, P, Q \rangle \neq \emptyset \Rightarrow T_{\mathcal{H}}(R) \nparallel \langle O, P, Q \rangle, \quad (2.66)$$

because, by (2.58), $O \notin T_{\mathcal{H}}(R)$. In particular, this implies that the plane $\langle O, P, Q \rangle$ has always transverse intersection (i.e., it is never tangent) with the hyperboloid \mathcal{H} .

Claim 2.29 *Suppose $P, Q \in \mathcal{H}$. Then $OP \parallel T_{\mathcal{H}}(Q) \Leftrightarrow OP \nparallel OQ$ and $\mathcal{C}(P, Q) = \mathcal{H} \cap \langle O, P, Q \rangle$ is an ellipse with (OP, OQ) as a pair of conjugate semi-diameters.*

Proof. \Rightarrow By the first part of Rem. 2.28, we already know that $OP \nparallel OQ$. This implies that $\mathcal{C}(P, Q) = \mathcal{H} \cap \langle O, P, Q \rangle$ is an admissible conic in the sense of Def. 2.6. In particular, $\mathcal{C}(P, Q)$ admits tangent line in each of its points. Besides, by the second part of Rem. 2.28, $T_{\mathcal{H}}(Q) \nparallel \langle O, P, Q \rangle$. Hence we deduce that the tangent line $T_{\mathcal{C}(P, Q)}(Q)$ satisfies

$$T_{\mathcal{C}(P, Q)}(Q) = T_{\mathcal{H}}(Q) \cap \langle O, P, Q \rangle, \quad (2.67)$$

because it is clear that $T_{\mathcal{C}(P, Q)}(Q) \subset T_{\mathcal{H}}(Q)$ and that $T_{\mathcal{C}(P, Q)}(Q) \subset \langle O, P, Q \rangle$. Then, since $OP \parallel \langle O, P, Q \rangle$ and we suppose $OP \parallel T_{\mathcal{H}}(Q)$, it follows that

$$OP \parallel T_{\mathcal{C}(P, Q)}(Q). \quad (2.68)$$

Moreover, by Claim 2.25, $OP \parallel T_{\mathcal{H}}(Q) \Leftrightarrow OQ \parallel T_{\mathcal{H}}(P)$. So with the same arguments used above we can prove that

$$OQ \parallel T_{\mathcal{C}(P, Q)}(P). \quad (2.69)$$

From this we deduce that $\mathcal{C}(P, Q)$ must be an ellipse, because (2.68) and (2.69) cannot both be true if $\mathcal{C}(P, Q)$ is a hyperbola or a pair of distinct, parallel lines which are symmetric with respect to the origin O .¹⁷ Having proved that $\mathcal{C}(P, Q)$ is an ellipse, again from (2.68) and (2.69), we deduce that (OP, OQ) is a pair of conjugate semi-diameters.

\Leftarrow The inverse implication is immediate from the properties of semi-diameters of an ellipse. \square

To proceed, taking into account Defs. 1.5, 1.8, we can state the following:

Claim 2.30 *Let $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ be a parallel projection. Let $Q_1, Q_2 \in \mathcal{H}$ such that $OQ_1 \parallel T_{\mathcal{H}}(Q_2)$ and let $P_1 = \Pi_{\mathbf{v}}(Q_1)$, $P_2 = \Pi_{\mathbf{v}}(Q_2)$. Then we have:*

(1) *If $OP_1 \nparallel OP_2$, then $\Pi_{\mathbf{v}} \Big|_{\langle O, Q_1, Q_2 \rangle} : \langle O, Q_1, Q_2 \rangle \rightarrow \omega$ defines an affine map such that*

$$\Pi_{\mathbf{v}}(\mathcal{C}(Q_1, Q_2)) = \mathcal{E}_{P_1, P_2}. \quad (2.70)$$

If we further suppose that $\Pi_{\mathbf{v}}$ is non-degenerate, then \mathcal{E}_{P_1, P_2} is tangent to $\mathcal{C}_{\mathbf{v}}$.

(2) *If $OP_1 \parallel OP_2$, then $\Pi_{\mathbf{v}}(\mathcal{C}(Q_1, Q_2))$ is the degenerate ellipse \mathcal{E}_{P_1, P_2} determined by the segments OP_1, OP_2 . If we further assume that $\Pi_{\mathbf{v}}$ is non-degenerate, then $\mathcal{C}_{\mathbf{v}}$ is necessarily a hyperbola and $\mathcal{C}_{\mathbf{v}}$ circumscribes \mathcal{E}_{P_1, P_2} (in the sense Def. 1.8).*

Proof. By Claim 2.29, we already know that $OQ_1 \nparallel OQ_2$ and that $\mathcal{C}(Q_1, Q_2)$ is an ellipse with conjugate semi-diameters OQ_1, OQ_2 . Besides, having $\Pi_{\mathbf{v}}(Q_1) = P_1$, $\Pi_{\mathbf{v}}(Q_2) = P_2$ with $OQ_1 \nparallel OQ_2$, the segments OP_1, OP_2 cannot both vanish. Hence we may consider the (eventually degenerate) ellipse \mathcal{E}_{P_1, P_2} .

¹⁷ If $\mathcal{C}(P, Q)$ is an hyperbola, just note what happens for $\mathcal{H} : \frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$. Given $Q = (x_q, y_q) \in \mathcal{H}$ and $P = (x_p, y_p)$, it follows that $OP \parallel T_{\mathcal{H}}(Q)$ iff $\frac{x_q x_p}{a^2} - \frac{y_q y_p}{b^2} = 0$. This means that $x_p = k \frac{y_q}{b^2}$, $y_p = k \frac{x_q}{a^2}$ for some $k \in \mathbb{R}$. But then $\frac{x_p^2}{a^2} - \frac{y_p^2}{b^2} = \frac{k^2}{a^2 b^2} (\frac{y_q^2}{b^2} - \frac{x_q^2}{a^2}) = -\frac{k^2}{a^2 b^2}$. Thus $P \notin \mathcal{H}$ regardless of the value of k . If $\mathcal{C}(P, Q)$ is a pair of distinct, parallel lines which are symmetric with respect to O , it is obvious that (2.68), (2.69) cannot hold.

(1) In this case, we have that

$$OP_1 \not\parallel OP_2 \quad \text{and} \quad \Pi_{\mathbf{v}}(Q_1) = P_1, \Pi_{\mathbf{v}}(Q_2) = P_2 \implies \mathbf{v} \not\parallel \langle O, Q_1, Q_2 \rangle. \quad (2.71)$$

So the restriction

$$\Pi_{\mathbf{v}} \Big|_{\langle O, Q_1, Q_2 \rangle} : \langle O, Q_1, Q_2 \rangle \rightarrow \omega$$

defines an affine transformation. Having $\Pi_{\mathbf{v}}(OQ_1) = OP_1$ and $\Pi_{\mathbf{v}}(OQ_2) = OP_2$, it is therefore clear that (2.70) holds. Next, we define

$$l = \langle O, Q_1, Q_2 \rangle \cap \pi_{\mathbf{v}}.$$

Noting that l is a straight line through the origin O in $\langle O, Q_1, Q_2 \rangle$, or all plane $\langle O, Q_1, Q_2 \rangle$, it is clear that

$$\mathcal{C}(Q_1, Q_2) \cap l \neq \emptyset, \quad (2.72)$$

because $\mathcal{C}(Q_1, Q_2) = \mathcal{H} \cap \langle O, Q_1, Q_2 \rangle$ is an ellipse, centered at O , in $\langle O, Q_1, Q_2 \rangle$. Hence

$$\mathcal{C}(Q_1, Q_2) \cap (\mathcal{H} \cap \pi_{\mathbf{v}}) = \mathcal{H} \cap \langle O, Q_1, Q_2 \rangle \cap \pi_{\mathbf{v}} = \mathcal{C}(Q_1, Q_2) \cap l \neq \emptyset. \quad (2.73)$$

This, in turn, implies that

$$\mathcal{E}_{P_1, P_2} \cap \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}) = \Pi_{\mathbf{v}}(\mathcal{C}(Q_1, Q_2)) \cap \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}) \neq \emptyset. \quad (2.74)$$

Then, if we suppose $\Pi_{\mathbf{v}}$ is non-degenerate, (2.74) gives

$$\mathcal{E}_{P_1, P_2} \cap \mathcal{C}_{\mathbf{v}} \neq \emptyset. \quad (2.75)$$

By Cor. 2.13, \mathcal{E}_{P_1, P_2} and $\mathcal{C}_{\mathbf{v}}$ are therefore tangent at any point of $\mathcal{E}_{P_1, P_2} \cap \mathcal{C}_{\mathbf{v}}$.

(2) Assuming $OP_1 \parallel OP_2$ it follows that $\zeta = \langle O, Q_1, Q_2 \rangle$ is the plane through O, P_1, P_2 and parallel to the vector \mathbf{v} . We can then apply part 1) of Claim 2.22 with $\mathcal{E} = \mathcal{C}(Q_1, Q_2)$. It easily follows that

$$\Pi_{\mathbf{v}}(\mathcal{C}(Q_1, Q_2)) = MN = \mathcal{E}_{P_1, P_2}, \quad (2.76)$$

because we already know that OQ_1, OQ_2 are conjugate semi-diameters of $\mathcal{C}(Q_1, Q_2)$ and, by (2.46), we have $|MN|^2 = 4(|OP_1|^2 + |OP_2|^2)$.

To proceed, since $\mathcal{C}(Q_1, Q_2)$ is an ellipse in $\zeta = \langle O, Q_1, Q_2 \rangle$, we can prove as in case (1) above that $\mathcal{E}_{P_1, P_2} \cap \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}) \neq \emptyset$. If we now suppose $\Pi_{\mathbf{v}}$ is non-degenerate, we have

$$MN \cap \mathcal{C}_{\mathbf{v}} \neq \emptyset. \quad (2.77)$$

This means that the line ℓ through M, N is a line through O such that $\ell \cap \mathcal{C}_{\mathbf{v}} \neq \emptyset$. Then, applying Claim 2.21, we see that $\mathcal{C}_{\mathbf{v}}$ must be a hyperbola, because $\mathcal{C}(Q_1, Q_2) = \mathcal{H} \cap \zeta$ is an ellipse.¹⁸ Finally, $\mathcal{C}_{\mathbf{v}}$ circumscribes \mathcal{E}_{P_1, P_2} . In fact, we have shown above that $MN \cap \mathcal{C}_{\mathbf{v}} \neq \emptyset$ and, by Cor. 2.13, we know that $MN \subset \mathbf{int}(\mathcal{C}_{\mathbf{v}})$. So we have $M, N \in \mathcal{C}_{\mathbf{v}}$, since M, N (as well $\mathcal{C}_{\mathbf{v}}$) are symmetrical with respect to the origin O . \square

Remark 2.31 *Under the assumptions of (1) of Claim 2.30 and taking into account Defs. 2.7, 2.8 and Cor. 2.13, if the projection $\Pi_{\mathbf{v}}$ is non-degenerate we can also say that:*

- $\mathcal{C}_{\mathbf{v}}$ is inscribed in \mathcal{E}_{P_1, P_2} , if $\mathcal{C}_{\mathbf{v}}$ is an ellipse. In particular, we have $\mathcal{C}_{\mathbf{v}} = \mathcal{E}_{P_1, P_2}$ if and only if $\pi_{\mathbf{v}} = \langle O, Q_1, Q_2 \rangle$.
- $\mathcal{C}_{\mathbf{v}}$ circumscribes \mathcal{E}_{P_1, P_2} if $\mathcal{C}_{\mathbf{v}}$ is a hyperbola.

¹⁸ Noting (2.76), we may deduce directly from Cor. 2.13 that $\mathcal{C}_{\mathbf{v}}$ must be a hyperbola. In fact, we have $O \in MN \subset \Pi_{\mathbf{v}}(\mathcal{H})$ and this means that $\mathcal{C}_{\mathbf{v}}$ cannot be an ellipse.

3 Hyperbolic Pohlke's projection in the circular case

In this section we will explicitly determine the hyperbolic Pohlke's projection $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ when in Def. 1.4 we also assume that two of the segments OP_1, OP_2, OP_3 are equal and perpendicular. Before proceeding we recall that, according to Def. 1.2, the points P, P' are $\pi_{\mathbf{v}}$ -symmetric if P, P' are obliquely symmetrical with respect to the plane $\pi_{\mathbf{v}}$, in the direction of \mathbf{v} . That is, $P' = \mathbf{S}_{\mathbf{v}}(P)$ where $\mathbf{S}_{\mathbf{v}}$ is the map introduced in Def. 2.3. Moreover, if $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ is a hyperbolic Pohlke's projection in the sense of Def. 1.4, we note that:

Remark 3.1 *Considering the symmetries $\mathbf{S}_{\mathbf{v}}$, with respect to $\pi_{\mathbf{v}}$, and $\mathbf{S}_{\mathbf{k}}$, with respect to the plane $\pi_{\mathbf{k}} = \omega$ (i.e. the usual symmetry with respect to ω), it is immediate to see that:*

- If $Q_1, Q_2, Q_3 \in \mathcal{H}$ satisfy the conditions (1.13), (1.14) of Def. 1.4 then, by Cor. 2.26, also the points $Q'_1 = \mathbf{S}_{\mathbf{v}}(Q_1)$, $Q'_2 = \mathbf{S}_{\mathbf{v}}(Q_2)$, $Q'_3 = \mathbf{S}_{\mathbf{v}}(Q_3)$ satisfy (1.13), (1.14). This means that in Def. 1.4 the triads Q_1, Q_2, Q_3 and Q'_1, Q'_2, Q'_3 are perfectly equivalent.
- Let us denote with $\bar{\Pi}_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ the symmetric projection with respect to ω , i.e.,

$$\bar{\Pi}_{\mathbf{v}}(P) = \Pi_{\mathbf{v}}(\mathbf{S}_{\mathbf{k}}(P)) \quad \text{for } P \in \mathbb{R}^3. \quad (3.1)$$

Then $\bar{\Pi}_{\mathbf{v}}$, with the points $\mathbf{S}_{\mathbf{k}}(Q_1)$, $\mathbf{S}_{\mathbf{k}}(Q_2)$ and $\mathbf{S}_{\mathbf{k}}(Q_3)$, still gives a hyperbolic Pohlke's projection for OP_1, OP_2, OP_3 . Observe also that if $\bar{\mathbf{v}} = \mathbf{S}_{\mathbf{k}}(\mathbf{v})$, then

$$\bar{\Pi}_{\mathbf{v}} = \Pi_{\bar{\mathbf{v}}} \quad \text{and} \quad \Pi_{\bar{\mathbf{v}}}(\mathcal{H} \cap \pi_{\bar{\mathbf{v}}}) = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}). \quad (3.2)$$

3.1 The circular case

We consider here the problem of determining the hyperbolic Pohlke's projections $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ in the *circular case*. More precisely, for $OP_1, OP_2, OP_3 \subset \omega$ such that

$$OP_1 \perp OP_2 \quad \text{and} \quad |OP_1| = |OP_2| = 1. \quad (3.3)$$

To begin with, according to Def. 1.4, we need to find $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ non-degenerate and then $Q_1, Q_2 \in \mathcal{H}(\rho)$ such that

$$\Pi_{\mathbf{v}}(Q_1) = P_1, \quad \Pi_{\mathbf{v}}(Q_2) = P_2 \quad \text{with} \quad OQ_1 \parallel T_{\mathcal{H}}(Q_2).$$

Assuming such a projection exists, from (1) of Claim 2.30 we deduce that \mathcal{E}_{P_1, P_2} must be tangent to $\mathcal{C}_{\mathbf{v}}$. Since \mathcal{E}_{P_1, P_2} is the circle with center O and radius $r = 1$, we have two possibilities:

- If $\mathcal{C}_{\mathbf{v}}$ is an ellipse (circle), having to be inscribed in \mathcal{E}_{P_1, P_2} (by (1) of Cor. 2.13), $\mathcal{C}_{\mathbf{v}}$ must have semi-major axis $a = 1$ (radius $r = 1$).
- If $\mathcal{C}_{\mathbf{v}}$ is a hyperbola, having to circumscribe \mathcal{E}_{P_1, P_2} (by (2) of Cor. 2.13), $\mathcal{C}_{\mathbf{v}}$ must have transverse semi-axis $a = 1$.

Then, from Claim 2.15 and Rem. 2.17, we conclude that:

Claim 3.2 *If (3.3) holds and if there is a hyperbolic Pohlke's projection for OP_1, OP_2, OP_3 (according to Def. 1.4), then $\rho = 1$. That is, we have*

$$\mathcal{H} = \mathcal{H}(1) = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 - z^2 = 1\}. \quad (3.4)$$

After this, again assuming that the hyperbolic Pohlke's projection $\Pi_{\mathbf{v}}$ exists, we note that (3.3), (3.4) imply $P_1, P_2 \in \mathcal{H}$. Thus we must have:

$$P_1 = Q_1 \text{ or } Q'_1 \quad \text{and} \quad P_2 = Q_2 \text{ or } Q'_2. \quad (3.5)$$

But to satisfy the conditions of Def. 1.4 it is necessary to set

$$Q_1 = P_1 \quad \text{and} \quad Q_2 = P_2 \quad (3.6)$$

or, equivalently, $Q'_1 = P_1$ and $Q'_2 = P_2$.²⁰ In fact, if we set $Q_1 = P_1$ and $Q'_2 = P_2$, applying Cor. 2.26, we find:

$$OQ_3 \parallel T_{\mathcal{H}}(Q'_1) \Leftrightarrow OQ_1 \parallel T_{\mathcal{H}}(Q'_3) \Leftrightarrow OP_1 \parallel T_{\mathcal{H}}(Q'_3), \quad (3.7)$$

$$OQ_2 \parallel T_{\mathcal{H}}(Q_3) \Leftrightarrow OQ'_2 \parallel T_{\mathcal{H}}(Q'_3) \Leftrightarrow OP_2 \parallel T_{\mathcal{H}}(Q'_3). \quad (3.8)$$

Now, from (2.60), it is easy to see that

$$OP_1 \parallel T_{\mathcal{H}}(Q'_3) \text{ and } OP_2 \parallel T_{\mathcal{H}}(Q'_3) \implies OQ'_3 \perp \omega \quad (3.9)$$

and the latter condition cannot be satisfied if $Q'_3 \in \mathcal{H}$. Since the same argument works if we try to define $Q'_1 = P_1$ and $Q_2 = P_2$, we are forced to assume (3.6). Moreover, by choosing $Q_1 = P_1$ and $Q_2 = P_2$, we must also have

$$Q_3 \neq Q'_3. \quad (3.10)$$

Indeed, if $Q_3 = Q'_3$, from Cor. 2.26 and condition (1.14) we easily deduce that $OP_1 \parallel T_{\mathcal{H}}(Q_3)$ and $OP_2 \parallel T_{\mathcal{H}}(Q_3)$. Hence, as in (3.9), we find $OQ_3 \perp \omega$ which cannot be satisfied. In conclusion, noting that (3.10) implies $Q_3Q'_3 \parallel \mathbf{v}$, we can say that:

Conditions 3.3 *Having fixed the points $Q_1 = P_1, Q_2 = P_2$ as in (3.6), to have a hyperbolic Pohlke's projection for OP_1, OP_2, OP_3 as in (3.3), it is necessary and sufficient to determine $Q_3, Q'_3 \in \mathcal{H}(1)$, $Q_3 \neq Q'_3$, such that the following conditions are true:*

(a) $OP_2 \parallel T_{\mathcal{H}}(OQ_3)$ and $OP_1 \parallel T_{\mathcal{H}}(OQ'_3)$ (i.e., $OQ_3 \parallel T_{\mathcal{H}}(OP'_1)$, by Cor. 2.26);

(b) $Q_3Q'_3 \not\parallel \omega$, because $Q_3Q'_3$ gives the direction of projection onto ω ;

(c) Q_3, Q'_3, P_3 are collinear (i.e., $\Pi_{\mathbf{v}}(Q_3) = \Pi_{\mathbf{v}}(Q'_3) = P_3$);

(d) $\mathbf{v} = \overrightarrow{Q_3Q'_3}$ gives a non-degenerate projection direction.

¹⁹ Given $Q \in \mathcal{H}$, by (2.60) we have $OP \parallel T_{\mathcal{H}}(Q) \Leftrightarrow x_P x_Q + y_P y_Q - z_P z_Q = 0$. Therefore, if $P_1, P_2 \in \omega$ are such that $OP_1 \perp OP_2$, then $OP_1 \parallel T_{\mathcal{H}}(P_2)$ and $OP_2 \parallel T_{\mathcal{H}}(P_1)$.

²⁰ In the following will not distinguish between these two possibilities because, by Rem. 3.1, we know that the triads Q_1, Q_2, Q_3 and Q'_1, Q'_2, Q'_3 are equivalent.

²¹ Given $Q = (x_Q, y_Q, z_Q) \in \mathcal{H}$ and $P_1, P_2 \in \omega$ such that $OP_1 \not\parallel OP_2$, we have that $OP_1, OP_2 \parallel T_{\mathcal{H}}(Q) \Leftrightarrow x_Q = y_Q = 0$. But the latter condition is equivalent to $OQ \perp \omega$.

3.2 Explicit determination of Π_v in the circular case

To proceed, we may suppose that the coordinate axes x, y are oriented in space such that

$$P_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad P_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \text{and} \quad P_3 = \begin{pmatrix} x \\ y \\ 0 \end{pmatrix}. \quad (3.11)$$

In particular, in this system we have

$$\overrightarrow{OP_3} = x \overrightarrow{OP_1} + y \overrightarrow{OP_2}. \quad (3.12)$$

Then, taking into account (2.60), we see that (a) in Cond. 3.3 is satisfied iff $Q_3 \in \mathcal{H} \cap \{y = 0\}$ and $Q'_3 \in \mathcal{H} \cap \{x = 0\}$. Thus we can express Q_3 and Q'_3 in the form

$$Q_3 = \begin{pmatrix} \cosh^* \alpha \\ 0 \\ \sinh \alpha \end{pmatrix} \quad \text{and} \quad Q'_3 = \begin{pmatrix} 0 \\ \cosh^* \beta \\ \sinh \beta \end{pmatrix} \quad (\alpha, \beta \in \mathbb{R}), \quad (3.13)$$

where, for simplicity, we have set

$$\cosh^* t \stackrel{\text{def}}{=} \pm \cosh t. \quad (3.14)$$

Having (3.13), it is clear that $Q_3 \neq Q'_3$ and that (b) in Cond. 3.3 holds iff

$$\sinh \alpha \neq \sinh \beta. \quad (3.15)$$

Besides, (c) of Cond. 3.3 is verified iff $P_3 = Q_3 + t \overrightarrow{Q_3 Q'_3}$ for some $t \in \mathbb{R}$. That is,

$$\begin{pmatrix} x \\ y \\ 0 \end{pmatrix} = \begin{pmatrix} \cosh^* \alpha \\ 0 \\ \sinh \alpha \end{pmatrix} + t \begin{pmatrix} -\cosh^* \alpha \\ \cosh^* \beta \\ \sinh \beta - \sinh \alpha \end{pmatrix} \quad \text{for some } t \in \mathbb{R}. \quad (3.16)$$

Now, assuming that (3.15) holds, we will first study the solvability of the system (3.16) and then we will verify if also (d) of in Cond. 3.3 is satisfied, i.e., if the projection direction found is non-degenerate. We will distinguish two cases to this aim:

3.3 Case $OP_3 \parallel OP_1$ or $OP_3 \parallel OP_2$

Suppose first $OP_3 \parallel OP_2$, that is $x = 0$. Since $\cosh^* \alpha \neq 0$, the first equation of (3.16) gives $t = 1$. Then, considering also the third equation, we find $\sinh \beta = 0$. Thus $\cosh^* \beta = \pm 1$ and $\sinh \alpha \neq 0$. Summarizing up, when $x = 0$ system (3.16) is solvable iff

$$P_3 = \pm \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}. \quad (3.17)$$

²² Just to have a simple parametrization of the entire hyperbolas $\mathcal{H} \cap \{y = 0\}$ and $\mathcal{H} \cap \{x = 0\}$, suitable for subsequent calculations.

If (3.17) holds, then we have

$$Q_3 = \begin{pmatrix} \cosh^* \alpha \\ 0 \\ \sinh \alpha \end{pmatrix} \text{ with } \alpha \neq 0, \quad Q'_3 = P_3. \quad (3.18)$$

Noting that the projection direction is given by $\mathbf{v} = \overrightarrow{Q_3 Q'_3} = -(\cosh^* \alpha) \mathbf{i} \pm \mathbf{j} - (\sinh \alpha) \mathbf{k}$, condition (d) is certainly true because $(\cosh^* \alpha)^2 + 1 - \sinh^2 \alpha = 2$. In conclusion, when $x = 0$ there are no hyperbolic Pohlke's projections if (3.17) fails, infinitely many if (3.17) holds. \square

Now suppose $OP_3 \parallel OP_1$, that is $y = 0$. Reasoning as in the previous case, we find that when $y = 0$ (3.16) is solvable iff

$$P_3 = \pm \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}. \quad (3.19)$$

If (3.19) holds, then we have

$$Q_3 = P_3, \quad Q'_3 = \begin{pmatrix} 0 \\ \cosh^* \beta \\ \sinh \beta \end{pmatrix} \text{ with } \beta \neq 0. \quad (3.20)$$

As above, (d) of Cond. 3.3 is true because $\mathbf{v} = \overrightarrow{Q_3 Q'_3} = \pm \mathbf{i} + (\cosh^* \beta) \mathbf{j} + (\sinh \beta) \mathbf{k}$. Thus there are no hyperbolic Pohlke's projections if (3.19) fails, infinitely many if (3.19) holds. \square

Summing up, taking into account Cond. 3.3, we have proved that:

Lemma 3.4 *If (3.3) is verified and $OP_3 \parallel OP_1$ (or $OP_3 \parallel OP_2$) then there are infinitely many hyperbolic Pohlke's projection for OP_1, OP_2, OP_3 if $|OP_3| = 1$, none if $|OP_3| \neq 1$.*

3.4 Case $OP_3 \not\parallel OP_1$ and $OP_3 \not\parallel OP_2$, that is $x, y \neq 0$

We note first that the condition $x, y \neq 0$ in (3.16) implies

$$\sinh \alpha, \sinh \beta \neq 0. \quad (3.21)$$

Indeed, if $\sinh \alpha = 0$, (3.15) and the third equation of (3.16) give $t = 0$. Then the second equation of (3.16) implies $y = 0$, contrary to our assumption. Similarly we find that $\sinh \beta \neq 0$.

Taking into account this fact, we deduce now a set of necessary conditions for the point P_3 to be collinear with Q_3, Q'_3 (i.e., to satisfy (3.16) for some $t \in \mathbb{R}$) when (3.15) and (3.21) hold. After that, we will prove that these conditions are also sufficient.

Assuming that (3.16) is true, by (3.15) and the third equation of (3.16), we have

$$t = \frac{\sinh \alpha}{\sinh \alpha - \sinh \beta}. \quad (3.22)$$

From (3.21) it follows that $t \neq 0, 1$ and that

$$x = \cosh^* \alpha - \frac{\cosh^* \alpha \sinh \alpha}{\sinh \alpha - \sinh \beta} \Rightarrow x \neq 0, \cosh^* \alpha; \quad (3.23)$$

$$y = \frac{\cosh^* \beta \sinh \alpha}{\sinh \alpha - \sinh \beta} \Rightarrow y \neq 0, \cosh^* \beta. \quad (3.24)$$

Then

$$\frac{x}{\cosh^* \alpha} + \frac{y}{\cosh^* \beta} = 1. \quad (3.25)$$

From (3.24), (3.25) we obtain

$$\begin{aligned} \cosh^* \alpha &= \frac{x \cosh^* \beta}{\cosh^* \beta - y}, \\ \sinh \alpha &= \frac{y \sinh \beta}{y - \cosh^* \beta}, \end{aligned} \quad (3.26)$$

because, by (3.24), we know that $y \neq \cosh^* \beta$.

Next, since $(\cosh^* \alpha)^2 - \sinh^2 \alpha = 1$, from (3.26) we have

$$x^2 (\cosh^* \beta)^2 - y^2 \sinh^2 \beta = (y - \cosh^* \beta)^2. \quad (3.27)$$

Hence, simplifying the expression above, we find

$$\left[(x^2 - y^2 - 1) \cosh^* \beta + 2y \right] \cosh^* \beta = 0. \quad (3.28)$$

Since $\cosh^* \beta \neq 0$ and (by (3.24)) $y \neq 0$, we deduce that:

$$x^2 - y^2 - 1 \neq 0, \quad (3.29)$$

and then

$$\cosh^* \beta = \frac{-2y}{x^2 - y^2 - 1}. \quad (3.30)$$

Noting that $x \neq 0$, $\cosh^* \alpha$ (see (3.23)) by similar arguments we can derive that

$$y^2 - x^2 - 1 \neq 0 \quad (3.31)$$

and

$$\cosh^* \alpha = \frac{-2x}{y^2 - x^2 - 1}. \quad (3.32)$$

Finally, since (3.21) is equivalent to $|\cosh^* \alpha| > 1$, $|\cosh^* \beta| > 1$, from the expressions (3.30), (3.32) we deduce the conditions:

$$(i) \left| \frac{2y}{x^2 - y^2 - 1} \right| > 1 \quad \text{and} \quad (ii) \left| \frac{2x}{y^2 - x^2 - 1} \right| > 1. \quad (3.33)$$

Summing up, we have:

Claim 3.5 *If (3.15), (3.21) are verified and if $P_3 = {}^t(x, y, 0)$ is given by formula (3.16), then the necessary conditions (3.29), (3.31) and (3.33) are satisfied.*

Definition 3.6 *We will denote with Σ the subset of \mathbb{R}^2 where (3.29), (3.31) hold, i.e.,*

$$\Sigma \stackrel{\text{def}}{=} \{(x, y) \mid x^2 - y^2 \neq \pm 1\}. \quad (3.34)$$

The solution region of (3.33) is given by the following:

Lemma 3.7 *A pair $(x, y) \in \Sigma$ satisfies the conditions (3.33) (i) and (ii) iff*

$$|x| + |y| > 1 \quad \text{and} \quad ||x| - |y|| < 1 \quad (3.35)$$

or, equivalently,

$$(x + y + 1)(x + y - 1)(x - y + 1)(x - y - 1) < 0. \quad (3.36)$$

Proof. The inequalities of (3.33) is invariant under symmetry with respect to the coordinate axes, i.e., on replacing (x, y) with $(\pm x, \pm y)$. So it is sufficient to solve (3.33) for $x, y \geq 0$. Besides, we can obtain the first of (3.33) from the second, and vice versa, by permutation of the variables x, y . Hence it is sufficient to solve the second inequality of (3.33).

To begin with, for $(x, y) \in \Sigma$ with $x, y \geq 0$, inequality (3.33) (ii) is equivalent to

$$-2x < y^2 - x^2 - 1 < 2x, \quad (3.37)$$

that is

$$(x - 1)^2 < y^2 < (x + 1)^2. \quad (3.38)$$

which, in turn, is equivalent to

$$|x - 1| < y < x + 1, \quad (3.39)$$

because $x + 1 \geq 0$ and $y \geq 0$. Next, it easy to see that

$$\{(x, y) \mid |x - 1| < y < x + 1\} = \{(x, y) \mid x + y > 1, |x - y| < 1\} \subset \{x, y \geq 0\}. \quad (3.40)$$

Thus, for $x, y \geq 0$, the solution region of (3.33) (ii) is given by

$$\Omega = \Sigma \cap \{(x, y) \mid x + y > 1, |x - y| < 1\}. \quad (3.41)$$

The set Ω in (3.41) is symmetric with respect to x, y . By the previous considerations, Ω gives also the solution region of (3.33) (i) for $x, y \geq 0$ and, taking into account the symmetry with respect to the axes, from this we immediately obtain (3.35). Finally, it is easy to verify the equivalence of (3.35) and (3.36), because they define the same subset of $\mathbb{R} \times \mathbb{R}$. \square

So far, we have proved that:

Claim 3.8 *If the conditions (3.15), (3.21) are verified and if $P = {}^t(x, y, 0)$ is given by (3.16), then $(x, y) \in \Sigma$ and*

$$g(x, y) \stackrel{\text{def}}{=} (x + y + 1)(x + y - 1)(x - y + 1)(x - y - 1) < 0. \quad (3.42)$$

The converse is also true:

Claim 3.9 *If a point $P = {}^t(x, y, 0)$ is such that $(x, y) \in \Sigma$ and (3.42) holds, then P is given by formula (3.16) for suitable α, β satisfying (3.15), (3.21).*

²³ Note that condition (3.42) implies $x, y \neq 0$.

Proof. Let us suppose that $(x, y) \in \Sigma$ satisfies (3.42). Then, by Lem. 3.7, there are (unique except for the sign) α, β such that

$$\cosh^* \alpha = \frac{-2x}{y^2 - x^2 - 1} \quad \text{and} \quad \cosh^* \beta = \frac{-2y}{x^2 - y^2 - 1}. \quad (3.43)$$

Since $|\cosh^* t| > 1 \Rightarrow \sinh t \neq 0$, condition (3.21) is certainly verified. With $\cosh^* \alpha, \cosh^* \beta$ such that (3.43) holds, the first two equations of (3.16) are satisfied by

$$t = \frac{y^2 - x^2 + 1}{2}. \quad (3.44)$$

Then, with t as in (3.44), the third equation of (3.16) is verified iff

$$\frac{\sinh \beta}{\sinh \alpha} = -\frac{y^2 - x^2 - 1}{x^2 - y^2 - 1}. \quad (3.45)$$

Now, introducing the expressions (3.43) inside the identity $\sinh^2 t = (\cosh^* t)^2 - 1$, we obtain

$$\sinh^2 \alpha = -\frac{g(x, y)}{(y^2 - x^2 - 1)^2} \quad \text{and} \quad \sinh^2 \beta = -\frac{g(x, y)}{(x^2 - y^2 - 1)^2}, \quad (3.46)$$

where $g(x, y)$ is the quantity defined in (3.42). Since we are assuming $g(x, y) < 0$, we may conclude that (3.45) holds iff

$$(\sinh \alpha, \sinh \beta) = \pm \left(\frac{\sqrt{-g(x, y)}}{y^2 - x^2 - 1}, \frac{-\sqrt{-g(x, y)}}{x^2 - y^2 - 1} \right). \quad (3.47)$$

Finally, it remains to note that for $(x, y) \in \Sigma$ the relation (3.45) gives also the inequality $\sinh \alpha \neq \sinh \beta$, i.e., condition (3.15). In conclusion, we have proved that there are α, β such that both conditions (3.15), (3.21) hold and $P = {}^t(x, y, 0)$ satisfies formula (3.16). \square

Recalling (3.13), (3.43) and (3.47), we may conclude the following:

Claim 3.10 *Let us suppose $x, y \neq 0$. Then system (3.16) with condition (3.15) is solvable $\Leftrightarrow (x, y) \in \Sigma$ and (3.42) holds. Moreover, if $(x, y) \in \Sigma$ and (3.42) holds,*

$$Q_3 = \frac{1}{y^2 - x^2 - 1} \begin{pmatrix} -2x \\ 0 \\ \delta \sqrt{-g(x, y)} \end{pmatrix} \quad \text{with } \delta = \pm 1, \quad (3.48)$$

$$Q'_3 = \frac{1}{y^2 - x^2 + 1} \begin{pmatrix} 0 \\ 2y \\ \delta \sqrt{-g(x, y)} \end{pmatrix}$$

where $g(x, y)$ is the function defined by (3.42).

Proof. As we have already observed at the beginning of section 3.4,

$$x, y \neq 0 \quad \text{and} \quad (3.15), (3.16) \quad \implies \quad (3.21). \quad (*)$$

Therefore, it is sufficient to apply Claim 3.8 and Claim 3.9. \square

The previous statement gives the necessary and sufficient conditions for the existence of Q_3, Q'_3 such that (a), (b), (c) of Cond. 3.3 hold, i.e., such that there is a projection $\Pi_{\mathbf{v}}$ satisfying (1.13) and (1.14) of Def. 1.4, when (3.3) holds and $P_3 = {}^t(x, y, 0)$ with $x, y \neq 0$. So, in order to have a hyperbolic Pohlke's projection, it only remains to verify if (d) of Cond. 3.3 holds when Q_3, Q'_3 are given by (3.48). To this end, noting (3.13), we write:

$$\mathbf{v} = \overrightarrow{Q_3 Q'_3} = -(\cosh^* \alpha) \mathbf{i} + (\cosh^* \beta) \mathbf{j} + (\sinh \beta - \sinh \alpha) \mathbf{k}, \quad (3.49)$$

with $\cosh^* \alpha, \cosh^* \beta$ as in (3.43) and $\sinh \alpha, \sinh \beta$ as in (3.47). Then we have:

Claim 3.11 *Let $P_3 = {}^t(x, y, 0)$ with $(x, y) \in \Sigma$ such that (3.42) holds. Then the projection direction $\mathbf{v} = l\mathbf{i} + m\mathbf{j} + n\mathbf{k}$ given by (3.49) satisfies*

$$l^2 + m^2 - n^2 = 4 \frac{x^2 + y^2 - 1}{(x^2 - y^2)^2 - 1}. \quad (3.50)$$

Proof. Assuming $(x, y) \in \Sigma$ and (3.42), the expressions (3.43) and (3.47) are well defined real numbers. Then writing \mathbf{v} as in (3.49) and using (3.47), we find that

$$\begin{aligned} l^2 + m^2 - n^2 &= (\cosh^* \alpha)^2 + (\cosh^* \beta)^2 - (\sinh \beta - \sinh \alpha)^2 \\ &= 2(1 + \sinh \alpha \sinh \beta) \\ &= 2 \left[1 + \frac{g(x, y)}{(y^2 - x^2 - 1)(x^2 - y^2 - 1)} \right] \\ &= 2 \left[1 - \frac{g(x, y)}{(x^2 - y^2)^2 - 1} \right] \\ &= 4 \frac{x^2 + y^2 - 1}{(x^2 - y^2)^2 - 1}. \quad \square \end{aligned} \quad (3.51)$$

Finally, taking into account Rem. 3.1, Claim 3.2, Cond.3.3 and summing up, we have:

Lemma 3.12 *If (3.3) is verified and if $OP_3 \not\parallel OP_1, OP_2$, then there is a hyperbolic Pohlke's projection $\Pi_{\mathbf{v}}$ for OP_1, OP_2, OP_3 if and only if*

$$\overrightarrow{OP_3} = x \overrightarrow{OP_1} + y \overrightarrow{OP_2}, \quad (3.52)$$

with (x, y) such that (3.42) holds and

$$f(x, y) \stackrel{\text{def}}{=} (x^2 + y^2 - 1)(x^2 - y^2 - 1)(x^2 - y^2 + 1) \neq 0. \quad (3.53)$$

If the conditions (3.42) and (3.53) are verified, then the hyperbolic Pohlke's projection $\Pi_{\mathbf{v}}$ is unique up to symmetry with respect to the plane ω . The conic $\mathcal{C}_{\mathbf{v}}$ is unique and $\mathcal{C}_{\mathbf{v}}$ is an ellipse if $f(x, y) < 0$, while $\mathcal{C}_{\mathbf{v}}$ is a hyperbola if $f(x, y) > 0$.

Proof. Let us first note that

$$f(x, y) \neq 0 \Leftrightarrow (x, y) \in \Sigma \quad \text{and} \quad x^2 + y^2 \neq 1. \quad (3.54)$$

Suppose now that (3.42), (3.53) are true. Then the existence of a projection $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ satisfying (1.13), (1.14) of Def. 1.4 follows from Claim 3.10. Thanks to Claim 3.11 and (3.54), the condition $f(x, y) \neq 0$ also implies that (d) of Cond. 3.3 is true, i.e., $\Pi_{\mathbf{v}}$ is non-degenerate. Hence $\Pi_{\mathbf{v}}$ is a hyperbolic Pohlke's projection for OP_1, OP_2, OP_3 .

Conversely, let $\Pi_{\mathbf{v}}$ be a hyperbolic Pohlke's projection for OP_1, OP_2, OP_3 . Taking into account Cond. 3.3 and the arguments at the beginning of Section 3.2, we deduce from Claim 3.10 that $(x, y) \in \Sigma$ and (3.42) holds. Furthermore, the points Q_3, Q'_3 are necessarily given by (3.48). Since $\Pi_{\mathbf{v}}$ is non-degenerate, (3.50) of Claim. 3.11 gives $x^2 + y^2 \neq 1$. By (3.54) we can finally see that also (3.53) holds.

As for the uniqueness of $\Pi_{\mathbf{v}}$, we recall that by Claim 3.2 we necessarily have $\rho = 1$, that is $\mathcal{H} = \mathcal{H}(1)$. Furthermore, the vector $\mathbf{v} = \overrightarrow{Q_3 Q'_3}$, given by Claim 3.10, is uniquely determined up to choosing the plus and minus sign in formula (3.48). This means that we can obtain only two projections, $\Pi_{\mathbf{v}}$ and $\bar{\Pi}_{\mathbf{v}}$, which are symmetric with respect to the plane ω (according to the second part of Rem. 3.1). Hence, taking into account that $\mathcal{H} = \mathcal{H}(1)$, from (3.2) we may conclude that $\mathcal{C}_{\mathbf{v}} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}})$ is unique. Finally, assuming that the hyperbolic Pohlke's projection exists, by Cor. 2.11 and (3.50) above, the conic $\mathcal{C}_{\mathbf{v}}$ is an ellipse or a hyperbola depending on whether it is $f(x, y) > 0$ or $f(x, y) < 0$. \square

4 Proof of Theorem 1.7

(1) \Rightarrow (2). It is sufficient to apply part (1) of Claim 2.30 first and then Cor. 2.13.

Indeed, since we are assuming $OP_i \nparallel OP_j$ ($1 \leq i < j \leq 3$) by the conditions (1.13), (1.14) of Def. 1.4 and part (1) of Claim 2.30, we have:

$$\Pi_{\mathbf{v}}(Q_1) = P_1, \Pi_{\mathbf{v}}(Q_2) = P_2 \quad \text{and} \quad OQ_1 \parallel T_{\mathcal{H}}(Q_2) \Rightarrow \Pi_{\mathbf{v}}(\mathcal{C}(Q_1, Q_2)) = \mathcal{E}_{P_1, P_2}, \quad (4.1)$$

$$\Pi_{\mathbf{v}}(Q_2) = P_2, \Pi_{\mathbf{v}}(Q_3) = P_3 \quad \text{and} \quad OQ_2 \parallel T_{\mathcal{H}}(Q_3) \Rightarrow \Pi_{\mathbf{v}}(\mathcal{C}(Q_2, Q_3)) = \mathcal{E}_{P_2, P_3} \quad (4.2)$$

and, noting that $\Pi_{\mathbf{v}}(Q'_1) = P_1$,

$$\Pi_{\mathbf{v}}(Q_3) = P_3, \Pi_{\mathbf{v}}(Q'_1) = P_1 \quad \text{and} \quad OQ_3 \parallel T_{\mathcal{H}}(Q'_1) \Rightarrow \Pi_{\mathbf{v}}(\mathcal{C}(Q_3, Q'_1)) = \mathcal{E}_{P_3, P_1}. \quad (4.3)$$

Furthermore, $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}$ are tangent to

$$\mathcal{C}_{\mathbf{v}} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}). \quad (4.4)$$

Then, since $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1} \subset \Pi_{\mathbf{v}}(\mathcal{H})$, by Cor. 2.13 we finally deduce that:

- $\mathcal{C}_{\mathbf{v}}$ is inscribed in $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}$ if $\mathcal{C}_{\mathbf{v}}$ is an ellipse;
- $\mathcal{C}_{\mathbf{v}}$ circumscribes $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}$ if $\mathcal{C}_{\mathbf{v}}$ is a hyperbola.

In conclusion $\mathcal{C} = \mathcal{C}_{\mathbf{v}}$ is a hyperbolic Pohlke's conic for OP_1, OP_2, OP_3 .

(2) \Rightarrow (1). This implication can be obtained by first applying Claim 2.15, Rem. 2.17 and then Claim 2.19 and the result of Appendix A, in particular Claim A.1.

Indeed, let \mathcal{C} be a hyperbolic Pohlke's conic for OP_1, OP_2, OP_3 . We fix $\mathcal{H} = \mathcal{H}(\rho)$ with

$$\rho = \text{major/transverse semi-axis of } \mathcal{C} \quad (\rho = \text{radius, if } \mathcal{C} \text{ is a circle}). \quad (4.5)$$

Then from the three cases of Rem. 2.17 we obtain, up to symmetry with respect to the plane ω , the projection direction, i.e., the vector \mathbf{v} . Moreover, by Claim 2.18, \mathbf{v} is non-degenerate. This means that we can realized \mathcal{C} as a projection of a section the hyperboloid $\mathcal{H} = \mathcal{H}(\rho)$. More precisely, we have:

$$\mathcal{C} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}) \stackrel{\text{def}}{=} \mathcal{C}_{\mathbf{v}}. \quad (4.6)$$

After that, we consider \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} and \mathcal{E}_{P_3, P_1} , which are tangent to $\mathcal{C}_{\mathbf{v}}$, by Def. 1.6. Starting with \mathcal{E}_{P_1, P_2} , by 1) of Claim 2.19 there is a plane π , through the origin O , such that $\mathcal{H} \cap \pi$ is an ellipse and $\Pi_{\mathbf{v}}(\mathcal{H} \cap \pi) = \mathcal{E}_{P_1, P_2}$.²⁴ Then, by 2) of Claim 2.19, there are $Q_1, Q_2 \in \mathcal{H} \cap \pi$ such that $\Pi(Q_1) = P_1$, $\Pi(Q_2) = P_2$ and OQ_1, OQ_2 are conjugate semi-diameters of the ellipse $\mathcal{H} \cap \pi$. This later fact implies $OQ_1 \parallel T_{\mathcal{C}_{\mathbf{v}}(Q_2)}$. Then

$$OQ_1 \parallel T_{\mathcal{C}_{\mathbf{v}}(Q_2)} \quad \text{and} \quad T_{\mathcal{C}_{\mathbf{v}}(Q_2)} \subset T_{\mathcal{H}}(Q_2) \Rightarrow OQ_1 \parallel T_{\mathcal{H}}(Q_2), \quad (4.7)$$

So the first condition of (1.14) is satisfied. To proceed further, we consider \mathcal{E}_{P_2, P_3} . Again from 1) and 2) of Claim 2.19 we can find a plane $\tilde{\pi}$, through O and Q_2 , such that $\mathcal{H} \cap \tilde{\pi}$ is an ellipse and $\Pi_{\mathbf{v}}(\mathcal{H} \cap \tilde{\pi}) = \mathcal{E}_{P_2, P_3}$. Besides, we can also find a point $Q_3 \in \mathcal{H} \cap \tilde{\pi}$ such that $\Pi(Q_3) = P_3$ and OQ_2, OQ_3 are conjugate semi-diameters of $\mathcal{H} \cap \tilde{\pi}$. As above, we deduce that

$$OQ_2 \parallel T_{\mathcal{H}}(Q_3). \quad (4.8)$$

So, the second condition of (1.14) holds. Finally, we consider the ellipse \mathcal{E}_{P_3, P_1} . Noting that

$$\Pi^{-1}(P_1) \cap \mathcal{H} = \{Q_1, Q'_1\}, \quad (4.9)$$

and reasoning as above, it is clear that at least one of the following must be true:

$$OQ_3 \parallel T_{\mathcal{H}}(Q_1) \quad \text{or} \quad OQ_3 \parallel T_{\mathcal{H}}(Q'_1). \quad (4.10)$$

But, by Claim A.1, we cannot have the sequence

$$OQ_1 \parallel T_{\mathcal{H}}(Q_2), \quad OQ_2 \parallel T_{\mathcal{H}}(Q_3) \quad \text{and} \quad OQ_3 \parallel T_{\mathcal{H}}(Q_1), \quad (4.11)$$

with $Q_1, Q_2, Q_3 \in \mathcal{H}$. Hence the second (and only the second) of (4.10) is true. In conclusion, we have found $Q_1, Q_2, Q_3 \in \mathcal{H}$ such that (1.13) and (1.14) hold.

4.1 The equivalence of (1), (2) with (3)

To prove that (1),(2) \Leftrightarrow (3) when OP_1, OP_2, OP_3 are non-parallel, we resort to an appropriate circular case. More precisely, let $N_1, N_2 \in \omega$ such that

$$ON_1 \perp ON_2 \quad \text{and} \quad |ON_1| = |ON_2| = 1. \quad (4.12)$$

Since $OP_1 \not\parallel OP_2$, we may consider the affine transformation $\Phi : \omega \rightarrow \omega$ defined by

$$\Phi(O + x\overrightarrow{OP_1} + y\overrightarrow{OP_2}) \stackrel{\text{def}}{=} O + x\overrightarrow{ON_1} + y\overrightarrow{ON_2} \quad \text{for} \quad x, y \in \mathbb{R}. \quad (4.13)$$

²⁴ From (2.36) we know that $\Pi_{\mathbf{v}}|_{\pi} : \pi \rightarrow \omega$ is an affine transformation. Hence $\mathcal{H} \cap \pi$ must be an ellipse.

It is clear that $\Phi(P_1) = N_1$, $\Phi(P_2) = N_2$. Besides, if $\overrightarrow{OP_3} = h\overrightarrow{OP_1} + k\overrightarrow{OP_2}$, then

$$N_3 \stackrel{\text{def}}{=} \Phi(P_3) = O + h\overrightarrow{ON_1} + k\overrightarrow{ON_2}. \quad (4.14)$$

Hence

$$\overrightarrow{ON_3} = h\overrightarrow{ON_1} + k\overrightarrow{ON_2} \quad \text{and} \quad ON_3 \nparallel ON_1, ON_2, \quad (4.15)$$

because $OP_3 \nparallel OP_1, OP_2$ (i.e., $h, k \neq 0$).

As it is known, an affine transformation maps conjugate semi-diameters of a central conic into conjugate semi-diameters of the transformed conic. This means that $\Phi(\mathcal{E}_{P_1, P_2}) = \mathcal{E}_{N_1, N_2}$, $\Phi(\mathcal{E}_{P_2, P_3}) = \mathcal{E}_{N_2, N_3}$ and $\Phi(\mathcal{E}_{P_3, P_1}) = \mathcal{E}_{N_3, N_1}$. Besides, if \mathcal{C} is a hyperbola (ellipse), with center O , which circumscribes (is inscribed in) \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} , \mathcal{E}_{P_3, P_1} , then $\Phi(\mathcal{C})$ is a hyperbola (ellipse) centered at O which circumscribes (is inscribed in) \mathcal{E}_{N_1, N_2} , \mathcal{E}_{N_2, N_3} , \mathcal{E}_{N_3, N_1} . The converse is also true, because $\Phi^{-1} : \omega \rightarrow \omega$ is still an affine transformation. Hence, according to Def. 1.6, we can state the following:

Claim 4.1 *If \mathcal{C} is a hyperbolic Pohlke's conic for OP_1, OP_2, OP_3 , then $\Phi(\mathcal{C})$ is a hyperbolic Pohlke's conic for ON_1, ON_2, ON_3 , and vice versa.*

(1), (2) \Rightarrow (3). Now let us suppose that (2) holds, namely that there is a hyperbolic Pohlke's conic \mathcal{C} for OP_1, OP_2, OP_3 . Then

$$\mathcal{C}_o = \Phi(\mathcal{C}) \quad (4.16)$$

is a hyperbolic Pohlke's conic for ON_1, ON_2, ON_3 . Hence, having already proved that (1) \Leftrightarrow (2), there is a hyperbolic Pohlke's projection for ON_1, ON_2, ON_3 . By (4.12) and (4.15) we can therefore apply Lem. 3.12 to ON_1, ON_2, ON_3 . Thus we conclude that h, k must satisfy the conditions (1.15) and (1.16).

(3) \Rightarrow (1), (2). Conversely, let us suppose that (3) hold, i.e., h, k satisfy the conditions (1.15) and (1.16). Then, by Lem. 3.12, there is a hyperbolic Pohlke's projection for ON_1, ON_2, ON_2 . By the equivalence (1) \Leftrightarrow (2), we deduce the existence of a hyperbolic Pohlke's conic, say \mathcal{C}_o , for ON_1, ON_2, ON_3 . Then,

$$\mathcal{C} = \Phi^{-1}(\mathcal{C}_o) \quad (4.17)$$

is a hyperbolic Pohlke's conic for OP_1, OP_2, OP_3 . Thus we have proved that (2) holds.

4.2 Uniqueness of $\Pi_{\mathbf{v}}$, \mathcal{C} and conic type of \mathcal{C}

The uniqueness properties of hyperbolic Pohlke's conic \mathcal{C} and of hyperbolic Pohlke's projection $\Pi_{\mathbf{v}}$ follow immediately from the circular case studied in Section 3. In fact, if we assume condition (3.3), by Claim 3.2 we necessarily have $\rho = 1$, that is $\mathcal{H} = \mathcal{H}(1)$. Besides, by Lem. 3.12, the projection direction, given by the vector $\overrightarrow{Q_3Q'_3}$ in (3.49), is unique up to symmetry with respect to the plane ω . That is, we have:

$$\mathbf{v} \parallel \mathbf{v}_+ \quad \text{or} \quad \mathbf{v} \parallel \mathbf{v}_- \quad \text{with} \quad \mathbf{v}_{\pm} = l\mathbf{i} + m\mathbf{j} \pm n\mathbf{k}, \quad (4.18)$$

for suitable l, m, n such that $n \neq 0$ and $l^2 + m^2 - n^2 \neq 0$. Therefore we have the uniqueness of the hyperbolic Pohlke's conic in the circular case, because

$$\mathcal{C} = \Pi_{\mathbf{v}_+}(\mathcal{H} \cap \pi_{\mathbf{v}_+}) = \Pi_{\mathbf{v}_-}(\mathcal{H} \cap \pi_{\mathbf{v}_-}). \quad (4.19)$$

Having proved the uniqueness in the circular case, applying the affine transformation $\Phi : \omega \rightarrow \omega$ introduced in (4.13), we deduce the uniqueness of the hyperbolic Pohlke's conic in general. As for the hyperbolic Pohlke's projection $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$, it is enough to recall that the hyperbolic Pohlke's conic \mathcal{C} uniquely determines the hyperboloid $\mathcal{H} = \mathcal{H}(\rho)$ and, up to symmetry with respect to the plane ω , the projection direction \mathbf{v} . See Rem. 2.17.

Finally, since \mathcal{C} and $\Phi(\mathcal{C})$ are conic of the same type, by Lem. 3.12 it is clear that the hyperbolic Pohlke's conic \mathcal{C} is an ellipse if $f(h, k) < 0$, while it is a hyperbola if $f(h, k) > 0$.

5 Proof of Theorem 1.10

We will first show that the equivalence (1) \Leftrightarrow (2) of Thm. 1.7 remains valid under the hypotheses of Thm. 1.10, if we allow degenerate ellipses, in the sense of Def. 1.8, and if we replace Def. 1.6 with Def. 1.9 as hyperbolic Pohlke's conic definition.

According to the hypotheses, we will assume that OP_1, OP_2, OP_3 are not contained in a line, but two of them are parallel to each other. More precisely, in the following we will suppose that

$$OP_1 \not\parallel OP_2 \quad \text{and} \quad OP_2 \parallel OP_3. \quad (5.1)$$

(1) \Rightarrow (2). We apply part (1) of Claim 2.30 (as in the proof of Thm. 1.7) if $OP_i \not\parallel OP_j$, and part (2) of Claim 2.30 if $OP_i \parallel OP_j$. To begin with, since we suppose $OP_1 \not\parallel OP_2$, by the conditions (1.13), (1.14) of Def. 1.4 and part (1) of Claim 2.30 we deduce that

$$\Pi_{\mathbf{v}}(\mathcal{C}(Q_1, Q_2)) = \mathcal{E}_{P_1, P_2} \quad \text{and} \quad \mathcal{C}_{\mathbf{v}} \text{ is tangent to } \mathcal{E}_{P_1, P_2}. \quad (5.2)$$

To proceed, we consider then the pair OP_2, OP_3 . In this case $OP_2 \parallel OP_3$, thus \mathcal{E}_{P_2, P_3} is a degenerate ellipse in the sense of Def. 1.8. Hence, by part (2) of Claim 2.30, we deduce that

$$\Pi_{\mathbf{v}}(\mathcal{C}(Q_2, Q_3)) = \mathcal{E}_{P_2, P_3} \quad \text{and that } \mathcal{C}_{\mathbf{v}} \text{ is a hyperbola circumscribing } \mathcal{E}_{P_2, P_3}.$$

Knowing that $\mathcal{C}_{\mathbf{v}}$ is a hyperbola, from (5.2) and Cor. 2.13 it also follows that $\mathcal{C}_{\mathbf{v}}$ circumscribes the ellipse \mathcal{E}_{P_1, P_2} . Finally, we consider the pair OP_3, OP_1 . Applying as above (1) of Claim 2.30 (if $OP_3 \not\parallel OP_1$) or (2) of Claim 2.30 (if $P_3 = O$), we find that

$$\Pi_{\mathbf{v}}(\mathcal{C}(Q_3, Q'_1)) = \mathcal{E}_{P_3, P_1} \quad \text{and } \mathcal{C}_{\mathbf{v}} \text{ circumscribes } \mathcal{E}_{P_3, P_1}. \quad (5.3)$$

In conclusion, we have proved that $\mathcal{C}_{\mathbf{v}}$ is a hyperbola circumscribing $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}$. Hence $\mathcal{C}_{\mathbf{v}}$ is a hyperbolic Pohlke's conic, in the sense of Def. 1.9, for OP_1, OP_2, OP_3 .

(2) \Rightarrow (1). Let \mathcal{C} be a hyperbolic Pohlke's conic in the sense of Def. 1.9. By applying Claim 2.15 and Rem. 2.17 (as in the proof of Thm. 1.7) we can determine the hyperboloid $\mathcal{H} = \mathcal{H}(\rho)$ and the projection direction, represented by \mathbf{v} , up to symmetry with respect to the plane ω . It automatically follows that \mathbf{v} is non-degenerate (by Claim 2.18) and that

$$\mathcal{C} = \Pi_{\mathbf{v}}(\mathcal{H} \cap \pi_{\mathbf{v}}) \stackrel{\text{def}}{=} \mathcal{C}_{\mathbf{v}}.$$

After this we consider the (eventually degenerate) ellipses $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}$. Using 1) and 2) of Claim 2.19 (if $OP_i \not\parallel OP_j$) or Claim 2.23 (if $OP_i \parallel OP_j$) and then the result of Appendix A, we can show that there are $Q_1, Q_2, Q_3 \in \mathcal{H}$ such that the conditions (1.13), (1.14) of Def. 1.4 are verified. In this way we prove that $\Pi_{\mathbf{v}}$ is a hyperbolic Pohlke's projection for OP_1, OP_2, OP_3 .

Conclusion of the proof. We can now prove that under the assumptions (5.1) there are infinite, distinct hyperbolic Pohlke's projections (conics) if $|OP_2| = |OP_3|$, none if $|OP_2| \neq |OP_3|$.

To this end, we resort to the circular case as in the proof of Thm. 1.7. Namely, since we assume $OP_1 \not\parallel OP_2$, we may consider the affine transformation $\Phi : \omega \rightarrow \omega$ defined in (4.13). In this case we have $\Phi(P_i) = N_i$, for $1 \leq i \leq 3$, with

$$ON_1 \perp ON_2, \quad |ON_1| = |ON_2| = 1 \quad \text{and} \quad ON_2 \parallel ON_3. \quad (5.4)$$

We note also that Claim 4.1 continues to hold even though we apply Def. 1.9 instead of Def. 1.6. So we still have that \mathcal{C} is a hyperbolic Pohlke's conic for OP_1, OP_2, OP_3 if and only if $\Phi(\mathcal{C})$ is a hyperbolic Pohlke's conic for ON_1, ON_2, ON_3 .²⁵

Now, having $ON_2 \parallel ON_3$, by Lem. 3.4 there are infinite, distinct hyperbolic Pohlke's projections for ON_1, ON_2, ON_3 if $|ON_3| = 1$, none if $|ON_3| \neq 1$. By the equivalence (1) \Leftrightarrow (2) proved above, it follows that there are infinite, distinct hyperbolic Pohlke's conics for ON_1, ON_2, ON_3 if $|ON_3| = 1$, none if $|ON_3| \neq 1$. Since

$$|ON_3| = 1 \quad \Leftrightarrow \quad |OP_3| = |OP_2|, \quad (5.5)$$

we deduce that, under assumption (5.1), there are infinite, distinct hyperbolic Pohlke's conics for OP_1, OP_2, OP_3 if $|OP_3| = |OP_2|$, none if $|OP_3| \neq |OP_2|$. Finally, again by the equivalence (1) \Leftrightarrow (2), the same holds for the hyperbolic Pohlke's projections.

A Appendix

In Def. 1.4 it may seem more natural to require the condition

$$OQ_1 \parallel T_{\mathcal{H}}(Q_2), \quad OQ_2 \parallel T_{\mathcal{H}}(Q_3) \quad \text{and} \quad OQ_3 \parallel T_{\mathcal{H}}(Q_1), \quad (A.1)$$

rather than (1.14). But, if we replace condition (1.14) with (A.1), then Def. 1.4 does not work. Indeed, even in the circular case (i.e., when OP_1, OP_2 satisfy (3.3)), there does not exist a projection $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$ satisfying (1.13) and (A.1).

To see this, suppose there is such a kind of projection $\Pi_{\mathbf{v}} : \mathbb{R}^3 \rightarrow \omega$. As in Section 3.1, we note that $\rho = 1$, because \mathcal{E}_{P_1, P_2} is a circle with center O and radius $r = 1$. That is

$$\mathcal{H} = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 - z^2 = 1\}. \quad (A.2)$$

Then, since $P_1, P_2 \in \mathcal{H}$, we must have:

$$P_1 = Q_1 \text{ or } Q'_1 \quad \text{and} \quad P_2 = Q_2 \text{ or } Q'_2. \quad (A.3)$$

But in this case both possibilities

$$1) \quad Q_1 = P_1 \text{ and } Q_2 = P_2 \quad (\text{or, equivalently, } Q'_1 = P_1, Q'_2 = P_2)$$

$$2) \quad Q_1 = P_1 \text{ and } Q_2 = P'_2 \quad (\text{or, equivalently, } Q'_1 = P_1, Q_2 = P_2)$$

²⁵ It is worth noting that if $\mathcal{E}_{P,Q}$ is a degenerate ellipse, then $\Phi(\mathcal{E}_{P,Q}) = \mathcal{E}_{\Phi(P), \Phi(Q)}$.

lead to contradictions.

In fact, if we set $Q_1 = P_1$ and $Q_2 = P_2$, applying Cor. 2.26, we find:

$$OP_1 \parallel T_{\mathcal{H}}(Q_3) \text{ and } OP_2 \parallel T_{\mathcal{H}}(Q_3), \quad (\text{A.4})$$

which, in turn, implies $OQ_3 \perp \omega$. But this later condition is impossible if $Q_3 \in \mathcal{H}$.¹⁷ Conversely, if we try to set $Q_1 = P_1$ and $Q'_2 = P_2$ (i.e., $Q_2 = P'_2$), we have

$$OP_1 \parallel T_{\mathcal{H}}(P_2), \quad OP_1 \parallel T_{\mathcal{H}}(P'_2) \quad (\text{A.5})$$

and, applying Cor. 2.26, also

$$OP_1 \parallel T_{\mathcal{H}}(Q_3), \quad OP_2 \parallel T_{\mathcal{H}}(Q'_3). \quad (\text{A.6})$$

Then, using coordinates axes x, y oriented in space such that (3.11) holds, (A.5) implies that the vector $\mathbf{v} = li + mj + nk$ satisfies:

- i) $\mathbf{v} \perp \mathbf{i}$ if $P_2 \neq P'_2$. In fact, if $P_2 \neq P'_2$ then $P_2P'_2 \parallel \mathbf{v}$. But, taking into account (2.60), condition (A.5) requires $\overrightarrow{P_2P'_2} \perp \mathbf{i}$.
- ii) $\mathbf{v} \perp \mathbf{j}$ if $P_2 = P'_2$. In fact, we have $P_2 = P'_2 \Leftrightarrow P_2 \in \pi_{\mathbf{v}} \Leftrightarrow m = 0$.

On the other hand, still from (2.60) and from (A.6), we have that $Q_3 \in \mathcal{H} \cap \{x = 0\}$ and $Q'_3 \in \mathcal{H} \cap \{y = 0\}$. So these points must be of the form

$$Q_3 = \begin{pmatrix} 0 \\ \cosh^* \alpha \\ \sinh \alpha \end{pmatrix} \quad \text{and} \quad Q'_3 = \begin{pmatrix} \cosh^* \beta \\ 0 \\ \sinh \beta \end{pmatrix}, \quad (\text{A.7})$$

for suitable α, β . But this means that

$$Q_3Q'_3 \not\perp \mathbf{i} \quad \text{and} \quad Q_3Q'_3 \not\perp \mathbf{j}, \quad (\text{A.8})$$

because $\cosh^* \alpha, \cosh^* \beta \neq 0$, in contradiction with the fact that $\mathbf{v} \parallel Q_3Q'_3$.

A.1 A more algebraic justification

More generally, we can prove that

Claim A.1 *There does not exist $Q_1, Q_2, Q_3 \in \mathcal{H}(\rho)$ such that*

$$OQ_1 \parallel T_{\mathcal{H}}(Q_2), \quad OQ_2 \parallel T_{\mathcal{H}}(Q_3), \quad OQ_3 \parallel T_{\mathcal{H}}(Q_1). \quad (\text{A.9})$$

Proof. In fact, writing $Q_1 = (x_1, y_1, z_1)$, $Q_2 = (x_2, y_2, z_2)$, $Q_3 = (x_3, y_3, z_3)$, by (2.60) we can reformulate (A.9) in the equivalent form:

$$\begin{cases} x_1x_2 + y_1y_2 - z_1z_2 = 0 \\ x_2x_3 + y_2y_3 - z_2z_3 = 0 \\ x_1x_3 + y_1y_3 - z_1z_3 = 0 \end{cases} \quad (\text{A.10})$$

Then, assuming $Q_1, Q_2 \in \mathcal{H}(\rho)$ are such that $OQ_1 \parallel T_{\mathcal{H}}(Q_2)$ (i.e., the first equation of (A.10) holds), we can show that there does not exist $Q_3 \in \mathcal{H}(\rho)$ such that $OQ_2 \parallel T_{\mathcal{H}}(Q_3)$ and $OQ_3 \parallel T_{\mathcal{H}}(Q_1)$ (i.e., the last two equations of (A.10) hold).

By contradiction let us suppose that such a point Q_3 exists. Noting that $OQ_1 \not\parallel OQ_2$ (see Rem. 2.28), from the last two equations of (A.10), we deduce that:

$$x_3 = \lambda \begin{vmatrix} y_1 & -z_1 \\ y_2 & -z_2 \end{vmatrix}, \quad y_3 = -\lambda \begin{vmatrix} x_1 & -z_1 \\ x_2 & -z_2 \end{vmatrix}, \quad z_3 = \lambda \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix}, \quad (\text{A.11})$$

for a suitable $\lambda \neq 0$. To proceed, it is not restrictive to assume that the coordinate axes are chosen such that $Q_1 = (x_1, 0, z_1)$, that is,

$$y_1 = 0. \quad (\text{A.12})$$

Hence (A.11) and (A.12) give

$$x_3 = \lambda z_1 y_2, \quad y_3 = \lambda(x_1 z_2 - z_1 x_2), \quad z_3 = \lambda x_1 y_2 \quad (\text{A.13})$$

and then

$$x_3^2 + y_3^2 - z_3^2 = \lambda^2 \left[z_1^2 y_2^2 + (x_1 z_2 - z_1 x_2)^2 - x_1^2 y_2^2 \right]. \quad (\text{A.14})$$

Now, we observe that

$$(z_1^2 - x_1^2) y_2^2 = -\rho^2 y_2^2 \quad \text{because} \quad x_1^2 - z_1^2 = \rho^2. \quad (\text{A.15})$$

So, if $x_2 = z_2 = 0$, from (A.14) and (A.15) we immediately obtain

$$x_3^2 + y_3^2 - z_3^2 = -\lambda^2 \rho^2 y_2^2 = -\lambda^2 \rho^4 < 0. \quad (\text{A.16})$$

Since we must have $x_3^2 + y_3^2 - z_3^2 = \rho^2$, the inequality (A.16) gives a contradiction. Conversely, let us suppose $(x_2, z_2) \neq (0, 0)$. With $y_1 = 0$ the first equation of (A.10) reads

$$\begin{vmatrix} x_1 & z_1 \\ z_2 & x_2 \end{vmatrix} = 0. \quad (\text{A.17})$$

Having assumed $(x_2, z_2) \neq (0, 0)$, we can deduce that

$$x_1 = \mu z_2, \quad z_1 = \mu x_2 \quad \text{for a suitable} \quad \mu \neq 0. \quad (\text{A.18})$$

This means that

$$(x_1 z_2 - z_1 x_2)^2 = \mu^2 (z_2^2 - x_2^2)^2. \quad (\text{A.19})$$

On the other hand, since $x_1^2 - z_1^2 = \rho^2$, from (A.18) we also have

$$\mu^2 (z_2^2 - x_2^2) = \rho^2. \quad (\text{A.20})$$

Taking into account (A.19), we therefore find

$$(x_1 z_2 - z_1 x_2)^2 = \rho^2 (z_2^2 - x_2^2) = \rho^2 (y_2^2 - \rho^2), \quad (\text{A.21})$$

because $x_2^2 + y_2^2 - z_2^2 = \rho^2$. Finally, from (A.14), (A.15) and (A.21), we obtain

$$x_3^2 + y_3^2 - z_3^2 = \lambda^2 \left[-\rho^2 y_2^2 + \rho^2 (y_2^2 - \rho^2) \right] = -\lambda^2 \rho^4 < 0, \quad (\text{A.22})$$

which gives the same contradiction of (A.16). \square

²⁶ Note that $x_2 = z_2 = 0 \Rightarrow y_2^2 = \rho^2$.

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